

SINGLE-CHIP, MULTIPLE-MESSAGES
VOICE RECORD/PLAYBACK DEVICES
4-, 5-, 6-, AND 8-MINUTE DURATION



#### 1. GENERAL DESCRIPTION

The ISD4003 ChipCorder® series provides high-quality, 3-volt, single-chip record/playback solutions for 4- to 8-minute messaging applications ideally for cellular phones and other portable products. The CMOS-based devices include an on-chip oscillator, anti-aliasing filter, smoothing filter, AutoMute® feature, audio amplifier, and high density multilevel Flash memory array. The ISD4003 series is designed to be used in a microprocessor- or microcontroller-based system. Address and control are accomplished through a Serial Peripheral Interface (SPI) or Microwire Serial Interface to minimize pin count

Recordings are stored into the on-chip Flash memory cells, providing zero-power message storage. This unique single-chip solution utilizes Winbond's patented multilevel storage technology. Voice and audio signals are directly stored onto memory array in their natural form, providing high-quality voice reproduction.

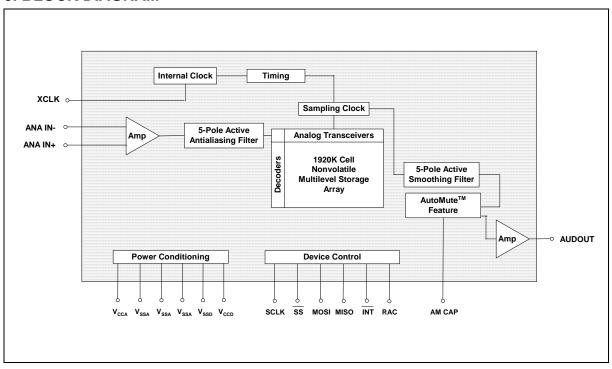
# ssess winbond sesses

#### 2. FEATURES

- Single-chip voice record/playback solution
- Single 3 volt supply
- · Low-power consumption
  - Operating current:
    - $I_{CC\_Play} = 15 \text{ mA (typical)}$
    - $I_{CC Rec} = 25 \text{ mA (typical)}$
  - Standby current:
    - $I_{CC\_Standby} = 1 \mu A \text{ (typical)}$
- Duration: 4, 5, 6, and 8 minutes
- · High-quality, natural voice/audio reproduction
- AutoMute feature provides background noise attenuation
- · No algorithm development required
- Microcontroller SPI or Microwire™ Serial Interface
- · Fully addressable to handle multiple messages
- Non-volatile message storage
- 100K record cycles (typical)
- 100-year message retention (typical)
- · On-chip oscillator
- Power-down feature to reduce power consumption
- · Available in die form, PDIP, SOIC, and TSOP
- · Packaged type: Lead-Free
- Temperature:
  - Commercial (die): 0°C to +50°C
  - Commercial (packaged units): 0°C to +70°C
  - Industrial (packaged units): -40°C to +85°C



### 3. BLOCK DIAGRAM



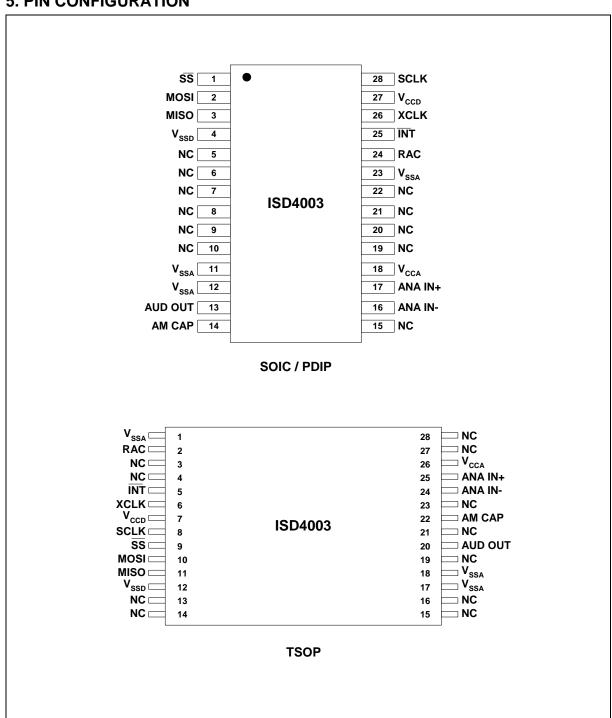
# **Esses winbond sesses**

4.	TA	BL	.E	OF	CO	NT	ΈN	<b>ITS</b>
т.			_	$\smile$				

1. GENERAL DESCRIPTION	2
2. FEATURES	3
3. BLOCK DIAGRAM	4
4. TABLE OF CONTENTS	5
5. PIN CONFIGURATION	6
6. PIN DESCRIPTION	7
7. FUNCTIONAL DESCRIPTION	12
7.1. Detailed Description	12
7.2. Serial Peripheral Interface (SPI) Description	13
7.2.1. OPCODES	14
7.2.2. SPI Diagrams	15
7.2.3. SPI Control and Output Registers	16
8. TIMING DIAGRAMS	18
9. ABSOLUTE MAXIMUM RATINGS	20
9.1. Operating Conditions	21
10. ELECTRICAL CHARACTERISTICS	22
10.1. Parameters For Packaged Parts	22
10.2. Parameters For Die	25
10.3. SPI AC Parameters	26
11. TYPICAL APPLICATION CIRCUIT	27
12. PACKAGING AND DIE INFORMATION	30
12.1. 28-Lead 300-Mil Plastic Small Outline IC (SOIC)	30
12.2. 28-Lead 600-Mil Plastic Dual Inline Package (PDIP)	31
12.3. 28-Lead 8x13.4mm Plastic Thin Small Outline Package (TSOP) Type 1 - IQC	32
12.4. 28-Lead 8x13.4mm Plastic Thin Small Outline Package (TSOP) Type 1	33
12.5. Die Information	34
13. ORDERING INFORMATION	36
14. VERSION HISTORY	37

# **Tables winbond seese**

#### 5. PIN CONFIGURATION





### 6. PIN DESCRIPTION

PIN NAME	PIN NO.		FUNCTION
	SOIC / PDIP	TSOP	
SS	1	9	<b>Slave Select</b> : This input, when LOW, will select the ISD4003 device.
MOSI	2	10	Master Out Slave IN: This is the serial input to the ISD4003 device when it is configured as slave. The master microcontroller places data on the MOSI line one half-cycle before the rising edge of SCLK for clocking into the device.
MISO	3	11	<b>Master In Slave Out</b> : This is the serial output (open drain) of the ISD4003 device. This output goes into a high-impedance state if the device is not selected.
V <sub>SSA</sub> / V <sub>SSD</sub>	11, 12, 23 / 4	1, 17, 18 / 12	<b>Ground</b> : The ISD4003 series utilizes separate analog and digital ground busses. The analog ground ( $V_{SSA}$ ) pins should be tied together as close as possible and connected through a low-impedance path to power supply ground. The digital ground ( $V_{SSD}$ ) pin should be connected through a separate low-impedance path to power supply ground. These ground paths should be large enough to ensure that the impedance between the $V_{SSA}$ pins and the $V_{SSD}$ pin is less than 3 Ω. The backside of the die is connected to $V_{SS}$ through the substrate. For chip-on-board design, the die attach area must be connected to $V_{SS}$ or left floating.
NC	5-10, 15, 19-22	3, 4, 13- 16, 19, 21, 23, 27, 28	Not connected
AUD OUT [1]	13	20	<b>Audio Output</b> : This pin provides an audio output of the stored data and is recommended be AC coupled. It is capable of driving a 5 K $\Omega$ impedance R <sub>EXT</sub> .

\_

Publication Release Date: July 16, 2007 Revision 1.3

 $<sup>^{[1]}</sup>$  The AUD OUT pin is always at 1.2 volts when the device is powered up. When in playback, the output buffer connected to this pin can drive a load as small as 5 KΩ. When in record, a built-in resistor connects AUD OUT to the internal 1.2-volt analog ground supply. This resistor is approximately 850 KΩ, but will vary somewhat according to the sample rate of the device. This relatively high impedance allows this pin to be connected to an audio bus without loading it down.

# **Esses winbond**

PIN NAME	PIN	I NO.	FUNCTION	
	SOIC / PDIP	TSOP		
AM CAP	14	22	AutoMute <sup>TM</sup> Feature: The AutoMute feature only applies for playback operation and helps to minimize noise (with 6 dB of attenuation) when there is no signal (i.e. during periods of silence). A 1 μF capacitor to ground is recommended to connect to the AM CAP pin.	
			This capacitor becomes a part of an internal peak detector which senses the signal amplitude. This peak level is compared to an internally set threshold to determine the AutoMute trip point. For large signals, the AutoMute attenuation is set to 0 dB automatically but 6 dB of attenuation occurs for silence. The 1 µF capacitor also affects the rate at which the AutoMute feature changes with the signal amplitude (or the attack time).	
			The AutoMute feature can be disabled by connecting the AM CAP pin directly to $V_{\text{CCA}}$ .	
ANA IN-	16	24	Inverting Analog Input: This pin transfers the signal into the device during recording via differential-input mode.	
			In this differential-input mode, a 16 mVp-p maximum input signal should be capacitively coupled to ANA IN- for optimal signal quality, as shown in Figure 1: ANA IN Modes. This capacitor value should be equal to that used on ANA IN+ pin. The input impedance at ANA IN- is normally 56 K $\Omega$ .	
			In the single-ended mode, ANA IN- should be capacitively coupled to $V_{\rm SSA}$ through a capacitor equal to that used on the ANA IN+ pin.	
ANA IN+	17	25	<b>Non-Inverting Analog Input</b> : This pin is the non-inverting analog input that transfers the signal to the device for recording. The analog input amplifier can be driven single ended or differentially.	
			In the single-ended input mode, a 32 mVp-p (peak-to-peak) maximum signal should be capacitively connected to this pin for optimal signal quality. The external capacitor associated with ANA IN+ together with the 3 K $\Omega$ input impedance are selected to give cutoff at the low frequency end of the voice passband.	
			In the differential-input mode, the maximum input signal at ANA IN+ should be 16 mVp-p capacitively coupled for optimal signal quality. The circuit connections for the two modes are shown in Figure 1.	

# **Esses winbond sesses**

PIN NAME	PIN NO.		FUNCTION	
	SOIC / PDIP	TSOP		
V <sub>CCA</sub> / V <sub>CCD</sub>	18 / 27	26 / 7	<b>Supply Voltage</b> : To minimize noises, the analog and digital circuits in the ISD4003 devices use separate power busses. These +3V busses are brought out to separate pins and should be tied together as close to the supply as possible. In addition, these supplies should be decoupled as close to the package as possible.	
RAC	24	2	Row Address Clock: This is an open drain output that provides the signal of a ROW with a 200 ms period for 8 KHz sampling frequency. (This represents a single row of memory.) This signal stays HIGH for 175 ms and stays LOW for 25 ms when it reaches the end of a row.	
			The RAC pin stays HIGH for 109.37 µsec and stays LOW for 15.63 µsec in Message Cueing mode (see Message Cueing section for detailed description). Refer to the AC Parameters table for RAC timing information at other sample rates.	
			When a record command is first initiated, the RAC pin remains HIGH for an extra $T_{RACL}$ period. This is due to the need of loading the internal sample and hold circuits in the device. This pin can be used for message management techniques.	
			A pull-up resistor is required to connect this pin to other device.	
INT	25	5	Interrupt: This is an open drain output pin. This pin goes LOW and stays LOW when an Overflow (OVF) or End or Message (EOM) marker is detected. Each operation that ends with an EOM or OVF will generate an interrupt. The interrupt will be cleared the next time an SPI cycle is initiated. The interrupt status can also be read by an R <sub>INT</sub> instruction.	
			A pull-up resistor is required to connect this pin to other device.	
			Overflow Flag (OVF) – The Overflow flag indicates that the end of memory has been reached during a record or playback operation.	
			End of Message (EOM) – The End of Message flag is set only during playback operation when an EOM is found. There are eight EOM flag position options per row.	

Publication Release Date: July 16, 2007 Revision 1.3



PIN NAME	PIN	I NO.		FUNCTION		
	SOIC / PDIP	TSOP				
XCLK	26	6	<b>External Clock Input</b> : The ISD4003 series is configured at the factory with an internal sampling clock frequency centered to $\pm 1$ percent of specification. The frequency is then maintained to a variation of $\pm 2.25$ percent over the entire commercial temperature and operating voltage ranges. The internal clock has a $-6/+4$ percent tolerance over the industrial temperature and voltage ranges. A regulated power supply is recommended for industrial temperature range parts. If greater precision is required, the device can be clocked through the XCLK pin as follows:			
			Part Number	Sample Rate	Required Clock	
			ISD4003-04M	8.0 kHz	1024 kHz	
			ISD4003-05M	6.4 kHz	819.2 kHz	
			ISD4003-06M	5.3 kHz	682.7 kHz	
			ISD4003-08M 4.0 kHz 512 kHz			
			These recommended clock rates should not be varied because the anti-aliasing and smoothing filters are fixed. Otherwise, aliasing problems can occur if the sample rate differs from the one recommended. The duty cycle on the input clock is not critical, as the clock is immediately divided by two. If the XCLK is not used, this input must be connected to ground.			rate the ately
SCLK	28	8	Serial Clock: This is It is generated microcontoller) and is in and out of the dev respectively. Data is edge of SCLK and sedge of SCLK.	by the mast s used to synchr rice through the latched into the	er device (typi conize the data trar MOSI and MISO li ISD4003 on the ri	cally nsfer ines, ising

# ass winbond s

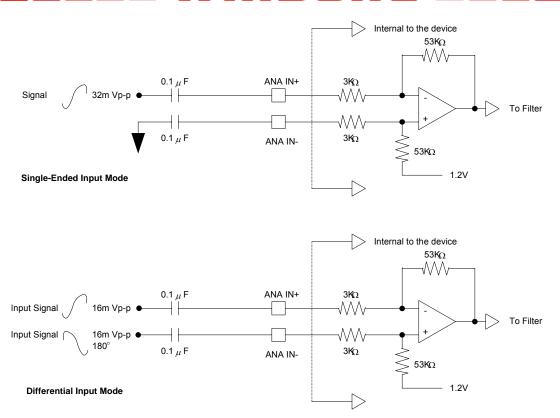


FIGURE 1: ISD4003 SERIES ANA IN MODES

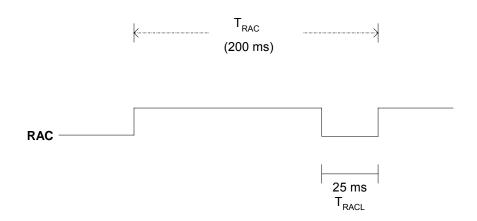


FIGURE 2: RAC TIMING WAVEFORM DURING NORMAL OPERATION

(example of 8KHz sampling rate)

Publication Release Date: July 16, 2007 Revision 1.3



#### 7. FUNCTIONAL DESCRIPTION

#### 7.1. DETAILED DESCRIPTION

#### **Audio Quality**

The Winbond's ISD4003 ChipCorder<sup>®</sup> series is offered at 8.0, 6.4, 5.3 and 4.0 kHz sampling frequencies, allowing the user a choice of speech quality options. Increasing the sampling frequency will produce better sound quality, but affects duration. Please refer to Table 1: Product Summary for details.

Analog speech samples are stored directly into on-chip non-volatile memory without the digitization and compression associated with other solutions. Direct analog storage provides higher quality reproduction of voice, music, tones, and sound effects than other solid-state solutions.

#### Duration

The ISD4003 Series is a single-chip solution with 4-, 5-, 6-, and 8-minute duration.

**TABLE 1: PRODUCT SUMMARY OF ISD4003 SERIES** 

Part Number	Duration (Minutes)	Sample Rate (kHz)	Typical Filter Pass Band (kHz) *
ISD4003-04M	4	8.0	3.4
ISD4003-05M	5	6.4	2.7
ISD4003-06M	6	5.3	2.3
ISD4003-08M	8	4.0	1.7

<sup>\*</sup> This is the –3dB point. This parameter is not checked during production testing and may vary due to process variations and other factors. Therefore, the customer should not rely upon this value for testing purposes.

#### Flash Storage

The ISD4003 series utilizes on-chip Flash memory, providing zero-power message storage. The message is retained for up to 100 years typically without power. In addition, the device can be rerecorded typically over 100,000 times.

#### **Memory Architecture**

The ISD4003 series contains a total of 1,920K Flash memory cells, which is organized as 1,200 rows of 1,600 cells each.



#### Microcontroller Interface

A four-wire (SCLK, MOSI, MISO & SS) SPI interface is provided for controlling and addressing functions. The ISD4003 is configured to operate as a peripheral slave device, with a microcontroller-based SPI bus interface. Read and write operations are controlled through this SPI interface. An interrupt signal (INT) and internal read only Status Register are provided for handshake purposes.

#### **Programming**

The ISD4003 series is also ideal for playback-only applications, where single- or multiple-messages playback is controlled through the SPI port. Once the desired message configuration is created, duplicates can easily be generated via a programmer.

#### 7.2. SERIAL PERIPHERAL INTERFACE (SPI) DESCRIPTION

The ISD4003 series operates via SPI serial interface with the following protocol.

First, the data transfer protocol assumes that the microcontroller's SPI shift registers are clocked on the falling edge of the SCLK. However, for the ISD4003, the protocols are as follows:

- 1. All serial data transfers begin with the falling edge of SS pin.
- 2. SS is held LOW during all serial communications and held HIGH between instructions.
- 3. Data is clocked in on the rising edge of the SCLK signal and clocked out on the falling edge of the SCLK signal, with LSB first.
- 4. Playback and record operations are initiated when the device is enabled by asserting the SS pin LOW, shifting in an opcode and an address data to the ISD4003 device (refer to the Opcode Summary in the following page).
- 5. The opcodes contain <11 address bits> and <5 control bits>.
- 6. Each operation that ends with an EOM or Overflow will generate an interrupt. The Interrupt will be cleared the next time a SPI cycle is initiated.
- 7. As Interrupt data is shifted out of the MISO pin, control and address data are simultaneously shifted into the MOSI pin. Care should be taken such that the data shifted in is compatible with current system operation. Because it is possible to read an interrupt data and start a new operation within the same SPI cycle.
- 8. An operation begins with the RUN bit set and ends with the RUN bit reset.
- 9. All operations begin after the rising edge of SS.



#### **7.2.1. OPCODES**

The available Opcodes are summarized as follows:

#### **TABLE 2: OPCODE SUMMARY**

Instructions	ОрО	Codes	Descriptions
	Address (11 bits) <a0 a10="" –=""></a0>	Control bits (5 bits) C0 C1 C2 C3 C4	
POWERUP	<xxxxxxxxxxxx< td=""><td>0 0 1 0 0</td><td>Power-Up: Device will be ready for an operation after <math>T_{\text{PUD}}</math>.</td></xxxxxxxxxxxx<>	0 0 1 0 0	Power-Up: Device will be ready for an operation after $T_{\text{PUD}}$ .
SETPLAY	<a0 a10="" –=""></a0>	0 0 1 1 1	Initiates playback from address <a0-a10>.</a0-a10>
PLAY	<xxxxxxxxxxxx< td=""><td>0 1 1 1 1</td><td>Playback from the current address (until EOM or OVF).</td></xxxxxxxxxxxx<>	0 1 1 1 1	Playback from the current address (until EOM or OVF).
SETREC	<a0 a10="" –=""></a0>	0 0 1 0 1	Initiates a record operation from address <a0-a10>.</a0-a10>
REC	<xxxxxxxxxxxx< td=""><td>0 1 1 0 1</td><td>Records from current address until OVF is reached or Stop command is sent.</td></xxxxxxxxxxxx<>	0 1 1 0 1	Records from current address until OVF is reached or Stop command is sent.
SETMC	<a0 a10="" –=""></a0>	1 0 1 1 1	Initiates Message Cueing (MC) from address <a0-a10>.</a0-a10>
MC <sup>[1]</sup>	<xxxxxxxxxxxx< td=""><td>1 1 1 1 1</td><td>Performs a Message Cueing from current location. Proceeds to the end of message (EOM) or enters OVF condition if no more messages are present.</td></xxxxxxxxxxxx<>	1 1 1 1 1	Performs a Message Cueing from current location. Proceeds to the end of message (EOM) or enters OVF condition if no more messages are present.
STOP	<xxxxxxxxxxxx< td=""><td>0 1 1 X 0</td><td>Stops the current operation.</td></xxxxxxxxxxxx<>	0 1 1 X 0	Stops the current operation.
STOPPWRDN	<xxxxxxxxxxxx< td=""><td>X 1 0 X 0</td><td>Stops the current operation and enters into standby (power-down) mode.</td></xxxxxxxxxxxx<>	X 1 0 X 0	Stops the current operation and enters into standby (power-down) mode.
RINT [2]	<xxxxxxxxxxx< td=""><td>0 1 1 X 0</td><td>Read Interrupt status bits: Overflow and EOM.</td></xxxxxxxxxxx<>	0 1 1 X 0	Read Interrupt status bits: Overflow and EOM.

#### Notes:

C0 = Message cueing

C1 = Ignore address bit

C2 = Master power control

C3 = Record or playback operation

C4 = Enable or disable an operation

<sup>[1]</sup> Message Cueing can be selected only at the beginning of a playback operation.

As the Interrupt data is shifted out of the ISD4003, control and address data are being shifted in. Care should be taken such that the data shifted in is compatible with current system operation. It is possible to read interrupt data and start a new operation at the same time. See Figures 5 - 8 for references.



### 7.2.2. SPI Diagrams

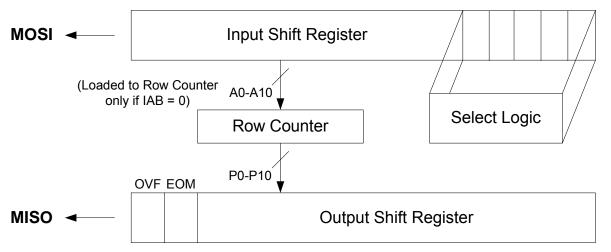
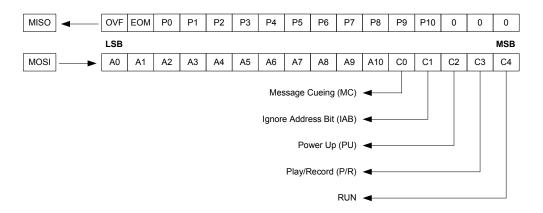


FIGURE 3: SPI INTERFACE SIMPLIFIED BLOCK DIAGRAM

The following diagram describes the SPI port and the control bits associated with it.



**FIGURE 4: SPI PORT** 



### 7.2.3. SPI Control and Output Registers

The SPI control register provides control of individual function such as play, record, message cueing, power-up, power-down, start, stop and ignore address pointer operations.

**TABLE 3: SPI CONTROL REGISTERS** 

Control Bit	Control Register	Bit	Device Function	
C0	MC		Message Cueing function	
	=	1	Enable Message Cueing	
	=	0	Disable Message Cueing	
C1	IAB <sup>[1]</sup>		Ignore Address bit	
	=	1	Ignore input address register (A0-A10)	
	=	0	Use the input address register (A0-A10)	
C2	PU		Power Up	
	=	1	Power-Up	
	=	0	Power-Down	
C3	P/R		Playback or Record	
	=	1	Play	
	=	0	Record	
C4	RUN		Enable or Disable an operation	
	=	1	Start	
	=	0	Stop	
Address Bits	A0-A10		Input address register	

**TABLE 4: SPI OUTPUT REGISTERS** 

Output Bits	Description
OVF	Overflow
EOM	End-of-Message
P0-P10	Output of the row pointer register

<sup>[1]</sup> When IAB (Ignore Address Bit) is set to 0, a playback or record operation starts from address (A0-A10). For consecutive playback or record, IAB should be changed to a 1 before the end of that row (see RAC timing). Otherwise the ISD4003 will repeat the operation from the same row address. For memory management, the Row Address Clock (RAC) signal and IAB can be used to move around the memory segments.



#### **Message Cueing**

Message cueing (MC) allows the user to skip through messages, without knowing the actual physical location of the messages. It will stop when an EOM marker is reached. Then, the internal address counter will point to the next message. Also, it will enter into OVF condition when it reaches the end of memory. In this mode, the messages are skipped 1,600 times faster than the normal playback mode.

#### **Power-Up Sequence**

The ISD4003 will be ready for an operation after power-up command is sent and followed by the  $T_{PUD}$  timing (25 ms for 8 KHz sampling rate). Refer to the AC timing table for other  $T_{PUD}$  values with respect to different sampling rates.

The following sequences are recommended for optimized Record and Playback operations.

#### Record Mode

- 1. Send POWERUP command.
- 2. Wait T<sub>PUD</sub> (power-up delay).
- 3. Send POWERUP command.
- 4. Wait 2 x T<sub>PUD</sub> (power-up delay).
- 5. a). Send SETREC command with address xx, or
  - b). Send REC command (recording from current location).
- 6. Send STOP command to stop recording.
- 7. Wait T<sub>STOP/PAUSE</sub>.

For 3 & 4), please refer to Apps Brief 39A: recorded pop elimination in the ISD4000 series.

For 5.a), the device will start recording at address xx and will generate an interrupt when an overflow (end of memory array) is reached, if no STOP command is sent before that. Then, it will automatic stop recording operation.

#### Playback Mode

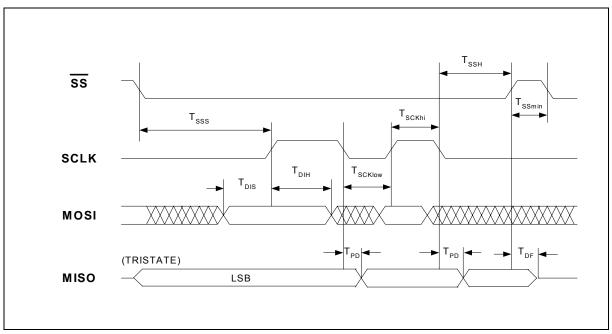
- 1. Send POWERUP command
- 2. Wait T<sub>PUD</sub> (power-up delay)
- 3. a). Send SETPLAY command with address xx, or
  - b). Send PLAY command (playback from current location).
- 4. a). Send STOP command to halt the playback operation, or
  - b). Wait for playback operation to stop automatically, when an EOM or OVF is reached.
- 5. Wait T<sub>STOP/PAUSE</sub>.

For 3.a), the device will start playback at address xx and it will generate an interrupt when an EOM or OVF is reached. It will then stop playback operation.

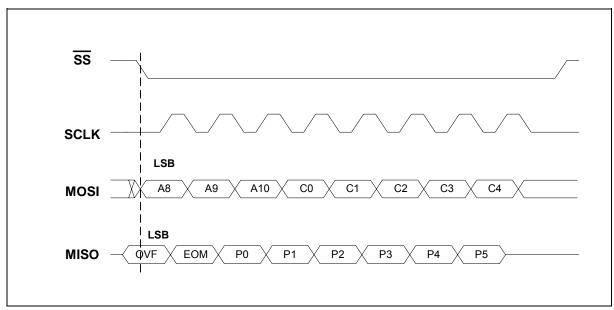
Publication Release Date: July 16, 2007 Revision 1.3



### 8. TIMING DIAGRAMS

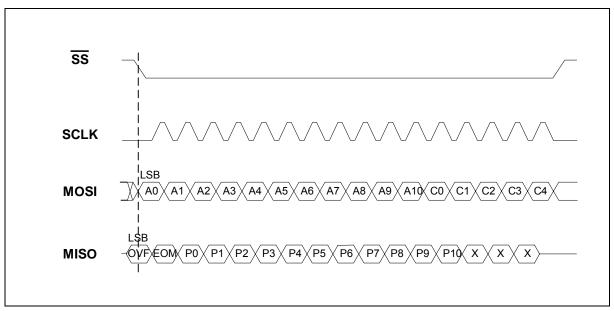


**FIGURE 5: TIMING DIAGRAM** 



**FIGURE 6: 8-BIT COMMAND FORMAT** 

# winbond |



**FIGURE 7: 16-BIT COMMAND FORMAT** 

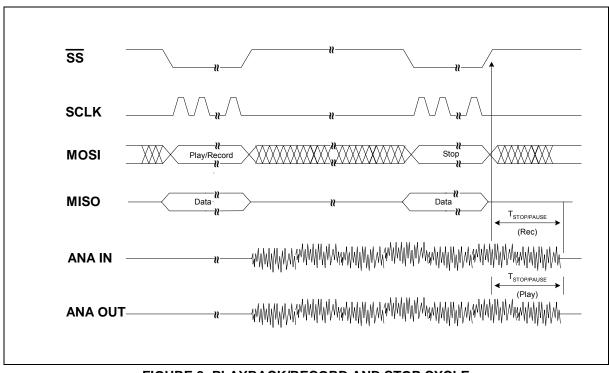


FIGURE 8: PLAYBACK/RECORD AND STOP CYCLE



### 9. ABSOLUTE MAXIMUM RATINGS

TABLE 5: ABSOLUTE MAXIMUM RATINGS (PACKAGED PARTS)

CONDITIONS	VALUES
Junction temperature	150°C
Storage temperature range	-65°C to +150°C
Voltage applied to any pin	$(V_{SS} - 0.3V)$ to $(V_{CC} + 0.3V)$
Voltage applied to any pin (Input current limited to ±20mA)	$(V_{SS} - 1.0V)$ to $(V_{CC} + 1.0V)$
Voltage applied to MOSI, SCLK, and SS pins (Input current limited to ±20mA)	(V <sub>SS</sub> –1.0V) to 5.5V
Lead temperature (soldering – 10 seconds)	300°C
$V_{CC} - V_{SS}$	-0.3V to +7.0V

#### **TABLE 6: ABSOLUTE MAXIMUM RATINGS (DIE)**

CONDITIONS	VALUES
Junction temperature	150°C
Storage temperature range	-65°C to +150°C
Voltage applied to any pad	$(V_{SS} - 0.3V)$ to $(V_{CC} + 0.3V)$
Voltage applied to any pad (Input current limited to $\pm 20$ mA)	$(V_{SS} - 1.0V)$ to $(V_{CC} + 1.0V)$
Voltage applied to MOSI, SCLK, and SS pins (Input current limited to ±20mA)	(V <sub>SS</sub> –1.0V) to 5.5V
$V_{CC} - V_{SS}$	-0.3V to +7.0V

Note: Stresses above those listed may cause permanent damage to the device. Exposure to the absolute maximum ratings may affect device reliability and performance. Functional operation is not implied at these conditions.



#### 9.1. OPERATING CONDITIONS

**TABLE 7: OPERATING CONDITIONS (PACKAGED PARTS)** 

CONDITIONS	VALUES
Commercial operating temperature range (Case temperature)	0°C to +70°C
Industrial operating temperature (Case temperature)	-40°C to +85°C
Supply voltage (V <sub>CC</sub> ) [1]	+2.7V to +3.3V
Ground voltage (V <sub>SS</sub> ) [2]	0V

### **TABLE 8: OPERATING CONDITIONS (DIE)**

CONDITIONS	VALUES
Commercial operating temperature range	0°C to +50°C
Supply voltage (V <sub>CC</sub> ) [1]	+2.7V to +3.3V
Ground voltage (V <sub>SS</sub> ) [2]	0V

 $<sup>^{[1]}</sup>$   $V_{CC} = V_{CCA} = V_{CCD}$ 

 $<sup>^{[2]}</sup>$   $V_{SS}$  =  $V_{SSA}$  =  $V_{SSD}$ 



### 10. ELECTRICAL CHARACTERISTICS

#### 10.1. PARAMETERS FOR PACKAGED PARTS

**TABLE 9: DC PARAMETERS** 

PARAMETERS	SYMBOLS	MIN <sup>[2]</sup>	TYP <sup>[1]</sup>	MAX <sup>[2]</sup>	UNITS	CONDITIONS
Input Low Voltage	V <sub>IL</sub>			V <sub>CC</sub> x 0.2	V	
Input High Voltage	V <sub>IH</sub>	V <sub>CC</sub> x 0.8			V	
Output Low Voltage	V <sub>OL</sub>			0.4	V	I <sub>OL</sub> = 10 μA
RAC, INT Output Low Voltage	V <sub>OL1</sub>			0.4	V	I <sub>OL</sub> = 1 mA
Output High Voltage	V <sub>OH</sub>	V <sub>CC</sub> - 0.4			V	I <sub>OH</sub> = -10 μA
V <sub>CC</sub> Current (Operating)	I <sub>CC</sub>					
- Playback			15	30	mA	R <sub>EXT</sub> = ∞ <sup>[3]</sup>
- Record			25	40	mA	R <sub>EXT</sub> = ∞ <sup>[3]</sup>
V <sub>CC</sub> Current (Standby)	I <sub>SB</sub>		1	10	μA	[3] [4]
Input Leakage Current	I <sub>IL</sub>			±1	μA	
MISO Tristate Current	I <sub>HZ</sub>		1	10	μA	
Output Load Impedance	R <sub>EXT</sub>	5			ΚΩ	
ANA IN+ Input Resistance	R <sub>ANA IN+</sub>	2.2	3.0	3.8	ΚΩ	
ANA IN- Input Resistance	R <sub>ANA IN-</sub>	40	56	71	ΚΩ	
ANA IN+ or ANA IN- to AUD OUT Gain	A <sub>ARP</sub>		23		dB	32 mVpp 1 KHz sinewave input <sup>[5]</sup>

Typical values @  $T_A = 25^{\circ}C$  and  $V_{CC} = 3.0V$ .

All Min/Max limits are guaranteed by Winbond via electronical testing or characterization. Not all specifications are 100 percent tested.

 $V_{CCA}$  and  $V_{CCD}$  connected together.

SS =  $V_{CCA} = V_{CCD}$ , XCLK = MOSI =  $V_{SSA} = V_{SSA}$  and all other pins floating.

<sup>[5]</sup> Measured with AutoMute feature disabled.

# massa winbond sassa

## **TABLE 10: AC PARAMETERS (Packaged Parts)**

OUADA OTEDIOTIO	0)/410.01.0					COMPUTIONS
CHARACTERISTIC	SYMBOLS	MIN <sup>[2]</sup>	TYP <sup>[1]</sup>	MAX <sup>[2]</sup>	UNITS	CONDITIONS
Sampling Frequency	Fs					(E)
ISD4003-04M			8.0		KHz	[5]
ISD4003-05M			6.4		KHz	[5]
ISD4003-06M			5.3		KHz	[5]
ISD4003-08M			4.0		KHz	[5]
Filter Pass Band	F <sub>CF</sub>	+	7.0		1112	
	FCF		2.4		121.1-	3 dB Roll-Off Point <sup>[3][7]</sup>
ISD4003-04M			3.4		KHz	3 dB Roll-Off Point 1
ISD4003-05M			2.7		KHz	3 dB Roll-Off Point[3][7]
ISD4003-06M			2.3		KHz	3 dB Roll-Off Point[3][7]
ISD4003-08M			1.7		KHz	3 dB Roll-Off Point[3][7]
Record Duration	T <sub>REC</sub>					
ISD4003-04M	ILLO		4		min	[6]
ISD4003-05M			5		min	[6]
ISD4003-06M			6		min	[6]
						[6]
ISD4003-08M	<u> </u>		8		min	
Playback Duration	T <sub>PLAY</sub>					100
ISD4003-04M		1	4		min	[6]
ISD4003-05M		1	5		min	[6]
ISD4003-06M		1	6		min	[6]
ISD4003-08M			8		min	[6]
Power-Up Delay	т —	1			111111	
	T <sub>PUD</sub>		25			
ISD4003-04M			25		msec	
ISD4003-05M			31.25		msec	
ISD4003-06M			37.5		msec	
ISD4003-08M			50		msec	
Stop or Pause in Record or Play	T <sub>STOP</sub> or T <sub>PAUSE</sub>					
ISD4003-04M	1310F VI IFAUSE		50		msec	
ISD4003-05M			62.5			
					msec	
ISD4003-06M			75		msec	
ISD4003-08M			100		msec	
RAC Clock Period	T <sub>RAC</sub>					
ISD4003-04M			200		msec	[10]
ISD4003-05M			250		msec	[10]
ISD4003-06M			300		msec	[10]
ISD4003-08M			400		msec	[10]
RAC Clock Low Time	_		400		111300	
	T <sub>RACL</sub>		0.5			
ISD4003-04M		1	25		msec	
ISD4003-05M		1	31.25		msec	
ISD4003-06M			37.5		msec	
ISD4003-08M			50		msec	
RAC Clock Period in Message	T <sub>RACM</sub>					
Cueing Mode		1				
ISD4003-04M		1	125		µsec	
ISD4003-04W		1	156.3			
		1			µsec	
ISD4003-06M		1	187.5		µsec	
ISD4003-08M	ļ	1	250		µsec	
RAC Clock Low Time in	T <sub>RACML</sub>	1				
Message Cueing Mode		1				
ISD4003-04M		1	15.63		µsec	
ISD4003-05M		1	19.53		µsec	
ISD4003-05W		1	23.44			
		1			µsec	
ISD4003-08M	<del>                                     </del>	<b>_</b>	31.25		µsec	
Total Harmonic Distortion	THD	1	1	2	%	32 mVpp 1 KHz
		1				sinewave input [11]
ANIA INI Immust N/c !!	1,7	1	1	20		Peak-to-Peak [4] [8] [9]
ANA IN Input Voltage	V <sub>IN</sub>	1		32	mV	reak-to-reak

Publication Release Date: July 16, 2007 Revision 1.3

# reses winbond sesses

- Typical values @  $T_A = 25$ °C,  $V_{CC} = 3.0$ V and timing measurement at 50%.
- [2] All Min/Max limits are guaranteed by Winbond via electrical testing or characterization. Not all specifications are 100 percent tested.
- [3] Low-frequency cutoff depends upon the value of external capacitors (see Pin Descriptions)
- [4] Single-ended input mode. In the differential input mode, V<sub>IN</sub> maximum for ANA IN+ and ANA IN- is 16 mVp-p.
- Sampling Frequency can vary as much as ±2.25 percent over the commercial temperature and voltage ranges, and –6/+4 percent over the industrial temperature and voltage ranges. For greater stability, an external clock can be utilized (see Pin Descriptions)
- Playback and Record Duration can vary as much as ±2.25 percent over the commercial temperature and voltage ranges, and –6/+4 percent over the industrial temperature and voltage ranges. For greater stability, an external clock can be utilized (see Pin Descriptions)
- Filter specification applies to the antialiasing filter and the smoothing filter. Therefore, from input to output, expect a 6 dB drop by nature of passing through both filters.
- The typical output voltage will be approximately 450 mVp-p with V<sub>IN</sub> at 32 mVp-p.
- [9] For optimal signal quality, this maximum limit is recommended.
- When a record command is sent,  $T_{RAC} = T_{RAC} + T_{RACL}$  on the first row address.
- [11] Measured with AutoMute feature disabled.



#### 10.2. PARAMETERS FOR DIE

#### **TABLE 11: DC PARAMETERS**

PARAMETERS [6]	SYMBOLS	MIN <sup>[2]</sup>	TYP <sup>[1]</sup>	MAX <sup>[2]</sup>	UNITS	CONDITIONS
Input Low Voltage	V <sub>IL</sub>			V <sub>CC</sub> x 0.2	V	
Input High Voltage	V <sub>IH</sub>	V <sub>CC</sub> x 0.8			V	
Output Low Voltage	V <sub>OL</sub>			0.4	V	I <sub>OL</sub> = 10 μA
RAC, INT Output Low Voltage	V <sub>OL1</sub>			0.4	V	I <sub>OL</sub> = 1 mA
Output High Voltage	V <sub>OH</sub>	V <sub>CC</sub> - 0.4			V	I <sub>OH</sub> = -10 μA
Operating Current	I <sub>CC</sub>					
-Playback			15	30	mA	R <sub>EXT</sub> = ∞ <sup>[3]</sup>
-Record			25	40	mA	R <sub>EXT</sub> = ∞ <sup>[3]</sup>
Standby Current	I <sub>SB</sub>		1	10	μA	[3] [4]
Total Harmonic Distortion	THD		1	2	%	32 mVpp 1 KHz sinewave input [5]
ANA IN+ or ANA IN- to AUD OUT Gain	A <sub>ARP</sub>		23		dB	32 mVpp 1 KHz sinewave input [5]

- Typical values @  $T_A$  = 25°C and  $V_{CC}$  = 3.0V. Sampling Frequency can vary as much as  $\pm 2.25$  percent over the commercial temperature and voltage ranges
- All Min/Max limits are guaranteed by Winbond via electrical testing or characterization. Not all specifications are 100 percent tested.
- $V_{CCA}$  and  $V_{CCD}$  connected together.
- SS =  $V_{CCA} = V_{CCD}$ , XCLK = MOSI =  $V_{SSA} = V_{SSA}$  and all other pins floating.
- [5] Measured with AutoMute feature disabled.
- The test coverage for die is limited to room temperature testing. The test conditions may differ from that of packaged parts.

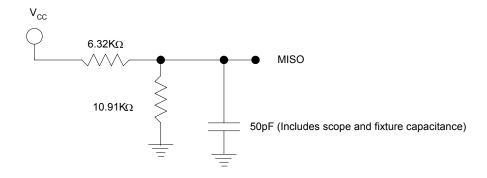


#### 10.3. SPI AC PARAMETERS

TABLE 12: AC PARAMETERS[1]

PARAMETER	SYMBOL	MIN	TYP	MAX	UNITS	CONDITIONS
SS Setup Time	T <sub>SSS</sub>	500			nsec	
SS Hold Time	T <sub>SSH</sub>	500			nsec	
Data in Setup Time	T <sub>DIS</sub>	200			nsec	
Data in Hold Time	T <sub>DIH</sub>	200			nsec	
Output Delay	T <sub>PD</sub>			500	nsec	
Output Delay to HighZ [2]	T <sub>DF</sub>			500	nsec	
SS HIGH	T <sub>SSmin</sub>	1			µsec	
SCLK High Time	T <sub>SCKhi</sub>	400			nsec	
SCLK Low Time	T <sub>SCKlow</sub>	400			nsec	
CLK Frequency	F <sub>0</sub>			1,000	KHz	_

- Typical values @  $T_A$  = 25°C,  $V_{CC}$  = 3.0V and timing measurement at 50%.
- [2] Tri-state test condition.





### 11. TYPICAL APPLICATION CIRCUIT

These application examples are for illustration purposes only. Winbond makes no representation or warranty that such application will be suitable for production.

Make sure all bypass capacitors are as close as possible to the package.

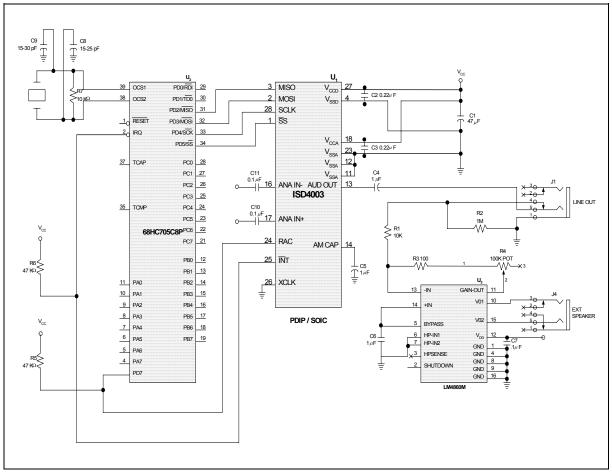


FIGURE 9: APPLICATION EXAMPLE USING SPI

# massa winbond sassa

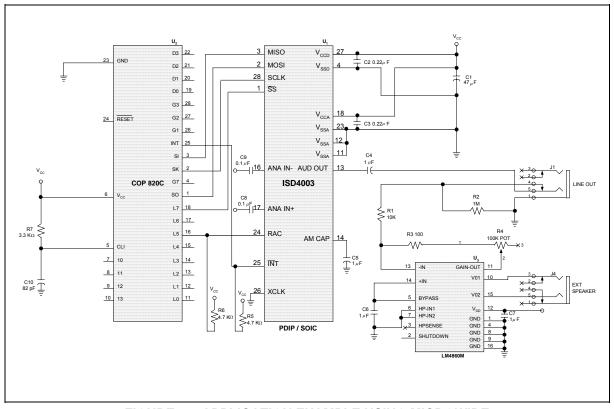


FIGURE 10: APPLICATION EXAMPLE USING MICROWIRE

# **Esses winbond sesse**

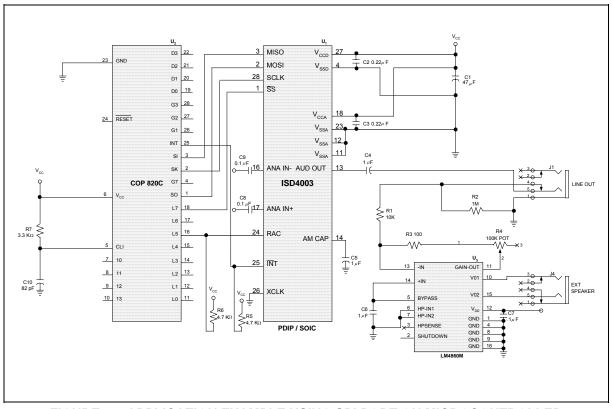
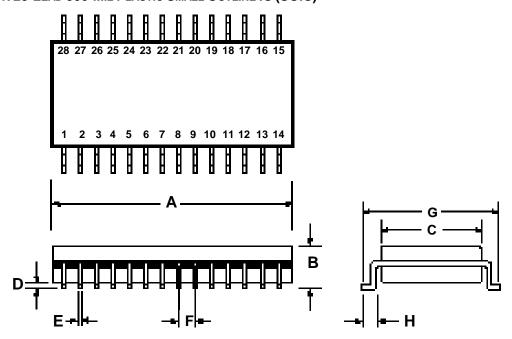


FIGURE 11: APPLICATION EXAMPLE USING SPI PORT ON MICROCONTROLLER

# **Bases winbond Bases**

### 12. PACKAGING AND DIE INFORMATION

12.1. 28-LEAD 300-MIL PLASTIC SMALL OUTLINE IC (SOIC)

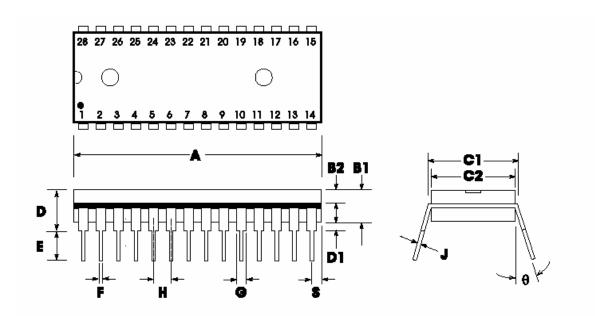


		INCHES		N	/ILLIMETER	S
	Min	Nom	Max	Min	Nom	Max
Α	0.701	0.706	0.711	17.81	17.93	18.06
В	0.097	0.101	0.104	2.46	2.56	2.64
С	0.292	0.296	0.299	7.42	7.52	7.59
D	0.005	0.009	0.0115	0.127	0.22	0.29
Е	0.014	0.016	0.019	0.35	0.41	0.48
F		0.050			1.27	
G	0.400	0.406	0.410	10.16	10.31	10.41
Н	0.024	0.032	0.040	0.61	0.81	1.02

Note: Lead coplanarity to be within 0.004 inches.

# s winbond sees

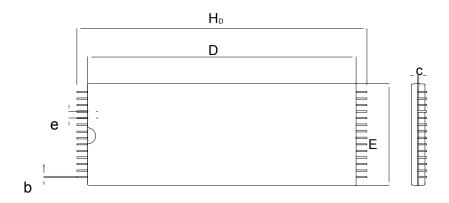
## 12.2. 28-LEAD 600-MIL PLASTIC DUAL INLINE PACKAGE (PDIP)



		INCHES		N	IILLIMETER:	S
	Min	Nom	Max	Min	Nom	Max
Α	1.445	1.450	1.455	36.70	36.83	36.96
B1		0.150			3.81	
B2	0.065	0.070	0.075	1.65	1.78	1.91
C1	0.600		0.625	15.24		15.88
C2	0.530	0.540	0.550	13.46	13.72	13.97
D			0.19			4.83
D1	0.015			0.38		
Е	0.125		0.135	3.18		3.43
F	0.015	0.018	0.022	0.38	0.46	0.56
G	0.055	0.060	0.065	1.40	1.52	1.62
Н		0.100			2.54	
J	0.008	0.010	0.012	0.20	0.25	0.30
S	0.070	0.075	0.080	1.78	1.91	2.03
q	0°		15°	0°		15°



## 12.3. 28-LEAD 8x13.4mm PLASTIC THIN SMALL OUTLINE PACKAGE (TSOP) TYPE 1 - IQC

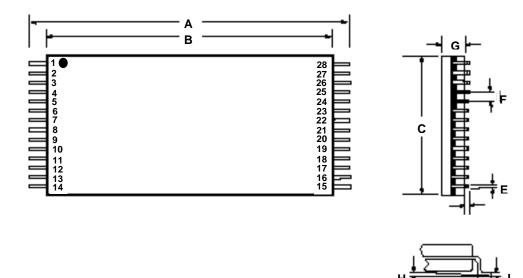




	Dimen	sion in	Inches	Dimension in mm			
Symbol	Min.	Nom.	Max.	Min.	Nom.	Max.	
Α	_		0.047			1.20	
<b>A</b> 1	0.002		0.006	0.05		0.15	
<b>A</b> 2	0.035	0.040	0.041	0.95	1.00	1.05	
b	0.007	0.008	0.011	0.17	0.20	0.27	
С	0.004	0.006	0.008	0.10	0.15	0.21	
D	0.461	0.465	0.469	11.70	11.80	11.90	
E	0.311	0.315	0.319	7.90	8.00	8.10	
H□	0.520	0.528	0.536	13.20	13.40	13.60	
е		0.022			0.55		
L	0.020	0.024	0.028	0.50	0.60	0.70	
L1		0.031			0.80		
Υ	0.000		0.004	0.00		0.10	
θ	0	3	5	0	3	5	

# winbond ====

## 12.4. 28-LEAD 8x13.4MM PLASTIC THIN SMALL OUTLINE PACKAGE (TSOP) TYPE 1



		INCHES		N	ILLIMETER:	S
	Min	Nom	Max	Min	Nom	Max
Α	0.520	0.528	0.535	13.20	13.40	13.60
В	0.461	0.465	0.469	11.70	11.80	11.90
С	0.311	0.315	0.319	7.90	8.00	8.10
D	0.002		0.006	0.05		0.15
Е	0.007	0.009	0.011	0.17	0.22	0.27
F		0.0217			0.55	
G	0.037	0.039	0.041	0.95	1.00	1.05
Н	0°	3°	6°	0°	3°	6°
I	0.020	0.022	0.028	0.50	0.55	0.70
J	0.004		0.008	0.10		0.21

Note: Lead coplanarity to be within 0.004 inches.

Publication Release Date: July 16, 2007 Revision 1.3



#### 12.5. DIE INFORMATION

#### ISD4003 Series

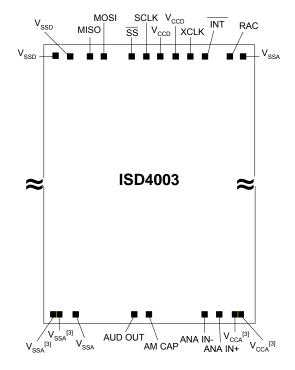
o Die Dimensions (with scribe line) [1]

X:  $166.6 \pm 1 \text{ mils}$ Y:  $274.9 \pm 1 \text{ mils}$ 

o Die Thickness  $^{[2]}$ 11.5  $\pm$  0.5 mils

Pad Opening

Single pad: 90 x 90 microns Double pad: 180 x 90 microns



- The backside of die is internally connected to V<sub>SS</sub>. It **MUST NOT** be connected to any other potential or damage may occur.
- [2] Die thickness is subject to change, please contact Winbond as this thickness may change in the future.
- Double bond is recommended if treated as one pad.



### **ISD4003 SERIES PAD COORDINATIONS**

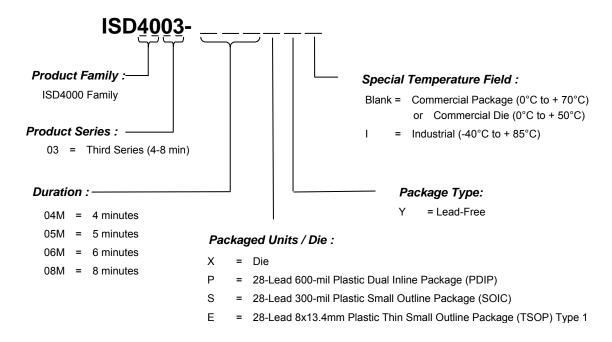
(with respect to die center)

Pad	Pad Description	X Axis (μm)	Y Axis (μm)
$V_{SSA}$	Analog Ground	1885.2	3273.7
RAC	Row Address Clock	1483.8	3273.7
INT	Interrupt	794.8	3273.7
XCLK	External Clock Input	564.8	3273.7
V <sub>CCD</sub>	Digital Power Supply	384.9	3273.7
V <sub>CCD</sub>	Digital Power Supply	169.5	3273.7
SCLK	Slave Clock	-14.7	3273.7
SS	Slave Select	-198.1	3273.7
MOSI	Master Out Slave In	-1063.7	3273.7
MISO	Master In Slave Out	-1325.6	3273.7
V <sub>SSD</sub>	Digital Ground	-1665.3	3273.7
V <sub>SSD</sub>	Digital Ground	-1836.9	3273.7
V <sub>SSA</sub> <sup>[1]</sup>	Analog Ground	-1943.1	-3272.4
V <sub>SSA</sub> <sup>[1]</sup>	Analog Ground	-1853.1	-3272.4
V <sub>SSA</sub>	Analog Ground	-1599.9	-3272.4
AUD OUT	Audio Output	281.9	-3272.4
AM CAP	AutoMute	577.3	-3272.4
ANA IN-	Inverting Analog Input	1449.3	-3272.4
ANA IN+	Noninverting Analog Input	1603.5	-3272.4
V <sub>CCA</sub> <sup>[1]</sup>	Analog Power Supply	1853.7	-3272.4
V <sub>CCA</sub> <sup>[1]</sup>	Analog Power Supply	1943.7	-3272.4

Double bond recommended if treated as one pad.



#### 13. ORDERING INFORMATION



When ordering the devices, please refer to the following valid ordering numbers and contact the local Winbond Sales Representatives for availability.

Туре	Duration	4 Minutes		5 Minutes		6 Minutes		8 Minutes	
	Package	Part #	Order#	Part #	Order #	Part #	Order #	Part #	Order #
	Die	ISD4003-04MX	14304X	ISD4003-05MX	14305X	ISD4003-06MX	I4306X	ISD4003-08MX	I4308X
	PDIP	ISD4003-04MPY	I4304PY	ISD4003-05MPY	14305PY	ISD4003-06MP	14306PY	ISD4003-08MPY	I4308PY
Free	SOIC	ISD4003-04MSY	14304SY	ISD4003-05MSY	14305SY	ISD4003-06MS	14306SY	ISD4003-08MSY	14308SY
ΙĠ		ISD4003-04MSYI	14304SYI	ISD4003-05MSYI	14305SYI	ISD4003-06MSI	14306SYI	ISD4003-08MSYI	14308SYI
Lea	TSOP	ISD4003-04MEY	14304EY	ISD4003-05MEY	14305EY	ISD4003-06ME	14306EY	ISD4003-08MEY	14308EY
		ISD4003-04MEYI	14304EYI	ISD4003-05MEYI	14305EYI	ISD4003-06MEI	14306EYI	ISD4003-08MEYI	14308EYI

For the latest product information, access Winbond worldwide website at http://www.winbond-usa.com



## **14. VERSION HISTORY**

VERSION	DATE	DESCRIPTION
0	June 2000	Initial version
1.0	Jan. 2004	Reformat the document.
		Add note for typical filter pass band.
		Add memory architecture description.
		Remove all CSP info.
		Revise RAC timing parameter for MC.
		Revise AutoMute: playback only.
		Revise SPI, opcodes sections, record & playback steps.
		Rename T <sub>RACLO</sub> to T <sub>RACL</sub> .
		Revise A <sub>ARP</sub> parameter.
		Revise DC & AC parameters tables for die.
		Revise die: (x,y) coordinates.
		Figures 9-11: revise V <sub>CCA</sub> and V <sub>CCD</sub> pin #.
		Revise Ordering Information.
1.1	Apr. 2005	Add lead-free parts.
		Revise the Ordering information.
		Update disclaim section.
1.2	Oct. 2005	Revise Packaging information.
1.3	Jul. 2007	Remove the leaded package options
		Remove the extended temperature option
		Update the external clock description
		Revise Ordering Information section

- 37 -

# winbond

Winbond products are not designed, intended, authorized or warranted for use as components in systems or equipment intended for surgical implantation, atomic energy control instruments, airplane or spaceship instruments, transportation instruments, traffic signal instruments, combustion control instruments, or for other applications intended to support or sustain life. Furthermore, Winbond products are not intended for applications wherein failure of Winbond products could result or lead to a situation wherein personal injury, death or severe property or environmental damage could occur.

Winbond customers using or selling these products for use in such applications do so at their own risk and agree to fully indemnify Winbond for any damages resulting from such improper use or sales.

The contents of this document are provided only as a guide for the applications of Winbond products. Winbond makes no representation or warranties with respect to the accuracy or completeness of the contents of this publication and reserves the right to discontinue or make changes to specifications and product descriptions at any time without notice. No license, whether express or implied, to any intellectual property or other right of Winbond or others is granted by this publication. Except as set forth in Winbond's Standard Terms and Conditions of Sale, Winbond assumes no liability whatsoever and disclaims any express or implied warranty of merchantability, fitness for a particular purpose or infringement of any Intellectual property.

The contents of this document are provided "AS IS", and Winbond assumes no liability whatsoever and disclaims any express or implied warranty of merchantability, fitness for a particular purpose or infringement of any Intellectual property. In no event, shall Winbond be liable for any damages whatsoever (including, without limitation, damages for loss of profits, business interruption, loss of information) arising out of the use of or inability to use the contents of this documents, even if Winbond has been advised of the possibility of such damages.

Application examples and alternative uses of any integrated circuit contained in this publication are for illustration only and Winbond makes no representation or warranty that such applications shall be suitable for the use specified.

The 100-year retention and 10K record cycle projections are based upon accelerated reliability tests, as published in the Winbond Reliability Report, and are neither warranted nor guaranteed by Winbond. This product incorporates SuperFlash®.

Information contained in this ISD<sup>®</sup> ChipCorder<sup>®</sup> datasheet supersedes all data for the ISD ChipCorder products published by ISD<sup>®</sup> prior to August, 1998.

This datasheet and any future addendum to this datasheet is(are) the complete and controlling ISD® ChipCorder® product specifications. In the event any inconsistencies exist between the information in this and other product documentation, or in the event that other product documentation contains information in addition to the information in this, the information contained herein supersedes and governs such other information in its entirety. This datasheet is subject to change without notice.

Copyright<sup>©</sup> 2005, Winbond Electronics Corporation. All rights reserved. ChipCorder<sup>®</sup> and ISD<sup>®</sup> are trademarks of Winbond Electronics Corporation. SuperFlash<sup>®</sup> is the trademark of Silicon Storage Technology, Inc. All other trademarks are properties of their respective owners.

Please note that all data and specifications are subject to change without notice.

All the trademarks of products and companies mentioned in this datasheet belong to their respective owners