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April 1, 2003

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**H8S/2368 Series
TFP-120
User System Interface Cable
(HS2368ECN61H)
for E6000 Emulator**

User's Manual

RENESAS

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Rev. 1.0
02/20/02
Hitachi, Ltd.

HS2368ECN61HE

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READ FIRST

- **READ this user's manual before using this user system interface cable.**
- **KEEP the user's manual handy for future reference.**

Do not attempt to use the user system interface cable until you fully understand its mechanism.

User System Interface Cable:

Throughout this document, the term "user system interface cable" shall be defined as the following product produced only by Hitachi, Ltd. excluding all subsidiary products.

- User system interface cable (HS2368ECN61H)

The user system or a host computer is not included in this definition.

Purpose of the User System Interface Cable:

This user system interface cable is for connecting the emulator station and user system. This user system interface cable must only be used for the above purpose.

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Target User of the User System Interface Cable:

This user system interface cable should only be used by those who have carefully read and thoroughly understood the information and restrictions contained in the user's manual. Do not attempt to use the user system interface cable until you fully understand its mechanism.

It is highly recommended that first-time users be instructed by users that are well versed in the operation of the user system interface cable.

LIMITED WARRANTY

Hitachi warrants its user system interface cables to be manufactured in accordance with published specifications and free from defects in material and/or workmanship. Hitachi will repair or replace any user system interface cables determined to be defective in material and/or workmanship. User system interface cables are wearing parts which Hitachi will not repair or replace if damaged and/or worn through use. The foregoing shall constitute the sole remedy for any breach of Hitachi's warranty. This warranty extends only to you, the original Purchaser. It is not transferable to anyone who subsequently purchases the user system interface cable from you. Hitachi is not liable for any claim made by a third party or made by you for a third party.

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Figures:

Some figures in this user's manual may show items different from your actual system.

Limited Anticipation of Danger:

Hitachi cannot anticipate every possible circumstance that might involve a potential hazard. The warnings in this user's manual and on the user system interface cable are therefore not all inclusive. Therefore, you must use the user system interface cable safely at your own risk.

SAFETY PAGE

READ FIRST

- **READ** this user's manual before using this user system interface cable.
- **KEEP** the user's manual handy for future reference.

Do not attempt to use the user system interface cable until you fully understand its mechanism.

DEFINITION OF SIGNAL WORDS



This is the safety alert symbol. It is used to alert you to potential personal injury hazards. Obey all safety messages that follow this symbol to avoid possible injury or death.



DANGER indicates an imminently hazardous situation which, if not avoided, will result in death or serious injury.



WARNING indicates a potentially hazardous situation which, if not avoided, could result in death or serious injury.



CAUTION indicates a potentially hazardous situation which, if not avoided, may result in minor or moderate injury.



CAUTION used without the safety alert symbol indicates a potentially hazardous situation which, if not avoided, may result in property damage.

NOTE emphasizes essential information.



WARNING

Observe the precautions listed below. Failure to do so will result in a FIRE HAZARD and will damage the user system and the emulator product or will result in PERSONAL INJURY. The USER PROGRAM will be LOST.

- 1. Do not repair or remodel the emulator product by yourself for electric shock prevention and quality assurance.**
- 2. Always switch OFF the E6000 emulator and user system before connecting or disconnecting any CABLES or PARTS.**
- 3. Always before connecting any CABLES, make sure that pin 1 on both sides are correctly aligned.**

Preface

Thank you for purchasing this user system interface cable (HS2368ECN61H) for the Hitachi's original microcomputer H8S/2368 series.

The HS2368ECN61H is a user system interface cable that connects an H8S/2678R series E6000 emulator (HS2678REPI61H; hereinafter referred to as the emulator) to the IC socket for a TFP-120 package for the H8S/2368 series MCU on the user system.

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Section 1 Configuration

CAUTION

Use an IC149-120-043-B51 socket (manufactured by YAMAICHI ELECTRONICS Co., Ltd) for the TFP-120 package IC socket on the user system.

Figure 1 shows the configuration of the HS2368ECN61H user system interface cable for the TFP-120 package.

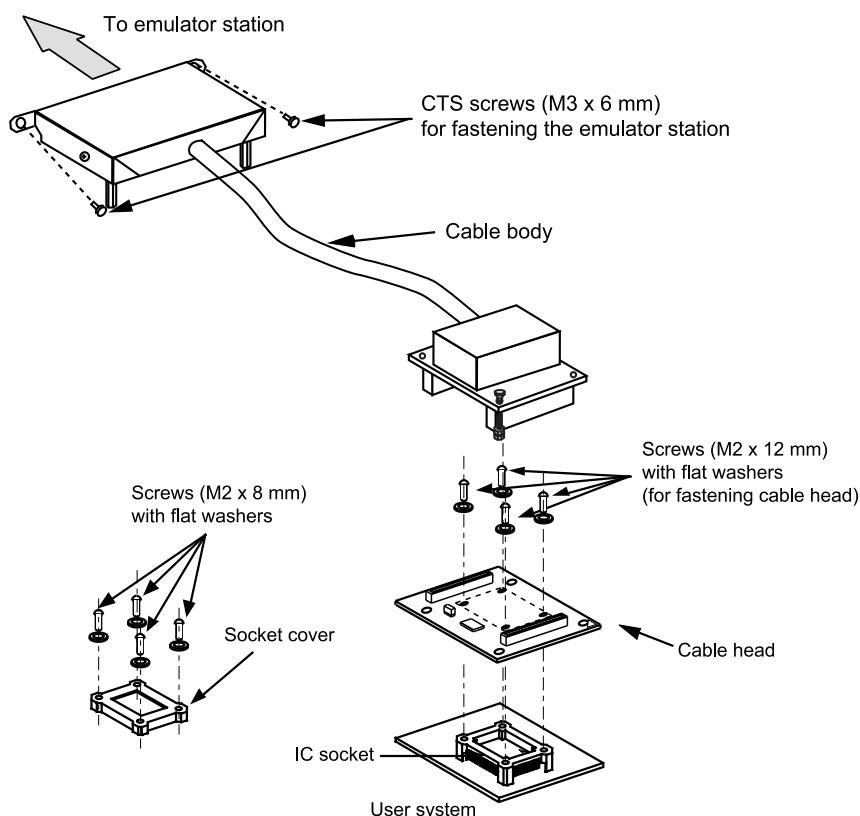


Figure 1 HS2368ECN61H User System Interface Cable

Table 1 lists the HS2368ECN61H components. Please make sure you have all of these components when unpacking.

Table 1 HS2368ECN61H Components

No.	Component	Quantity	Remarks
1	Cable body	1	
2	Cable head	1	
3	IC socket	1	For the TFP-120 package
4	Socket cover	1	For installing a TFP-120 packaged MCU
5	Screws (M2 x 12 mm)	4	For fastening cable head (with four flat washers)
6	Screws (M2 x 8 mm)	4	For installing a TFP-120 packaged MCU (with four flat washers)
7	CTS screws (M3 x 6 mm)	2	For fastening the emulator station
8	Documentation	1	User's manual for HS2368ECN61H (this manual)

Section 2 Connection Procedures

2.1 Connecting User System Interface Cable to Emulator Station

WARNING

Observe the precautions listed below. Failure to do so will result in a FIRE HAZARD and will damage the user system and the emulator product or will result in PERSONAL INJURY. The USER PROGRAM will be LOST.

- 1. Always switch OFF the user system and the emulator product before the USER SYSTEM INTERFACE CABLE is connected to or removed from any part. Before connecting, make sure that pin 1 on both sides are correctly aligned.**
- 2. The user system interface cable dedicated to the emulator must be used.**

To connect the cable body to the emulator station, follow the instructions below.

1. Make sure the user system and emulator station are turned off.

CAUTION

When connecting or removing the user system interface cable, apply force only in the direction suitable for connection or removal, while making sure not to bend or twist the cable or connectors. Otherwise, the connectors will be damaged.

2. After making sure the direction of the cable body connector is correct, firmly insert the cable body connector into the emulator station socket, and fasten the emulator station with two CTS screws (M3 x 6 mm) (figure 2).

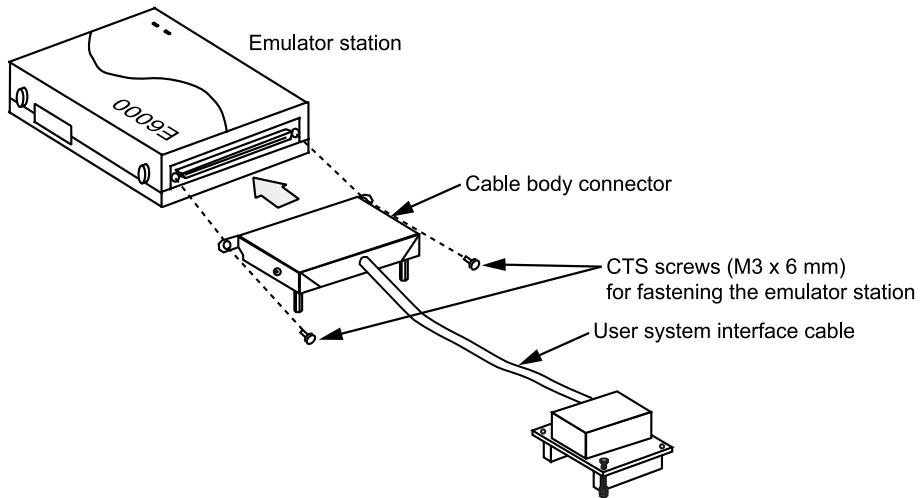


Figure 2 Connecting User System Interface Cable to Emulator Station

2.2 Connecting User System Interface Cable to User System

WARNING

Always switch OFF the user system and the emulator product before the USER SYSTEM INTERFACE CABLE is connected to or removed from any part. Before connecting, make sure that pin 1 on both sides are correctly aligned. Failure to do so will result in a FIRE HAZARD and will damage the user system and the emulator product or will result in PERSONAL INJURY. The USER PROGRAM will be LOST.

To connect the cable head to the user system, follow the instructions below.

2.2.1 Installing IC Socket

After checking the location of pin 1 on the IC socket, apply epoxy resin adhesive to the bottom of the IC socket for a TFP-120 package, and fasten it to the user system before soldering.

2.2.2 Soldering IC Socket

After fastening, solder the IC socket for a TFP-120 package to the user system. Be sure to completely solder the leads so that the solder slopes gently over the leads and forms solder fillets. (Use slightly more solder than the MCU.)

2.2.3 Inserting Cable Head

CAUTION

Check the location of pin 1 before inserting.

Align pin 1 on the IC socket for an TFP-120 package on the user system with pin 1 on the user system interface cable head, and insert the user system interface cable head into the IC socket on the user system, as shown in figure 3.

2.2.4 Fastening Cable Head

CAUTION

- 1. Use a Philips-type screwdriver whose head matches the screw head.**
- 2. The tightening torque must be 0.098 N·m or less.**
If the applied torque cannot be accurately measured, stop tightening when the force required to turn the screw becomes significantly greater than that needed when first tightening. If a screw is tightened too much, the screw head may break or an IC socket contact error may be caused by a crack in the IC socket solder.
- 3. If the emulator does not operate correctly, cracks might have occurred in the solder. Check conduction with a tester and re-solder the IC socket if necessary.**

Fasten the user system interface cable head to the IC socket for an TFP-120 package on the user system with the four screws (M2 x 12 mm; with flat washers) provided. Each screw should be tightened a little at a time, alternating between screws on opposing corners. Take special care, such as manually securing the IC socket soldered area, to prevent the soldered IC socket from being damaged by overtightening the screws or twisting the components.

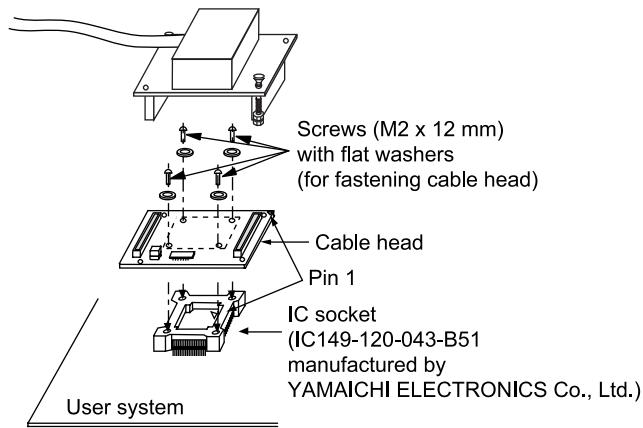


Figure 3 Connecting User System Interface Cable to User System

2.2.5 Fastening Cable Body

Connect the cable body to the cable head.

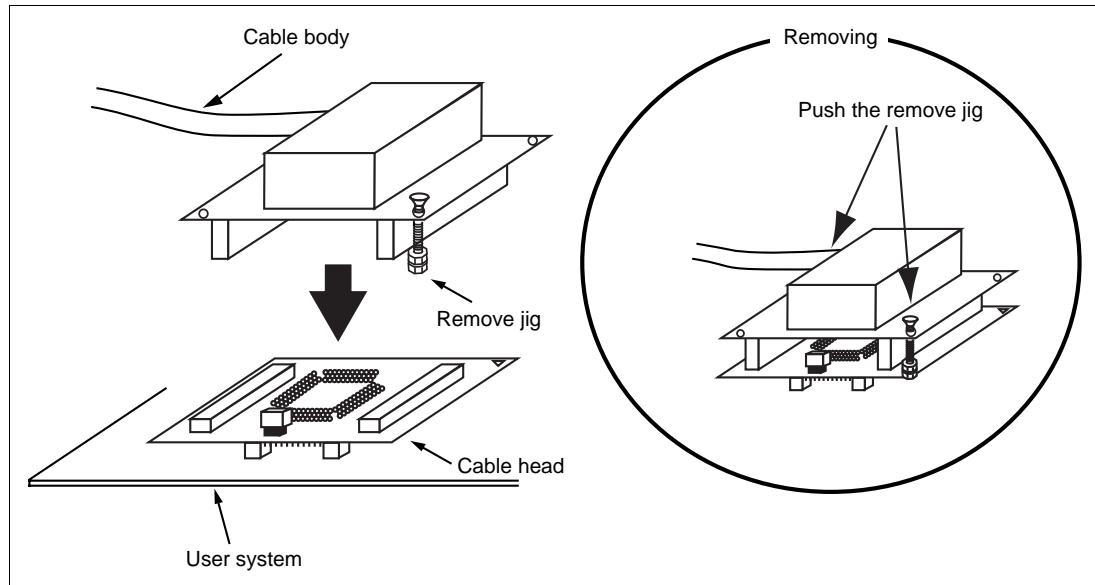


Figure 4 Fastening Cable Body

2.3 Recommended Dimensions for User System Mount Pad

Figure 5 shows the recommended dimensions for the mount pad (footprint) for the user system with an IC socket for a TFP-120 package (IC149-120-043-B51: manufactured by YAMAICHI ELECTRONICS Co., Ltd.). Note that the dimensions in figure 5 are somewhat different from those of the actual chip's mount pad.

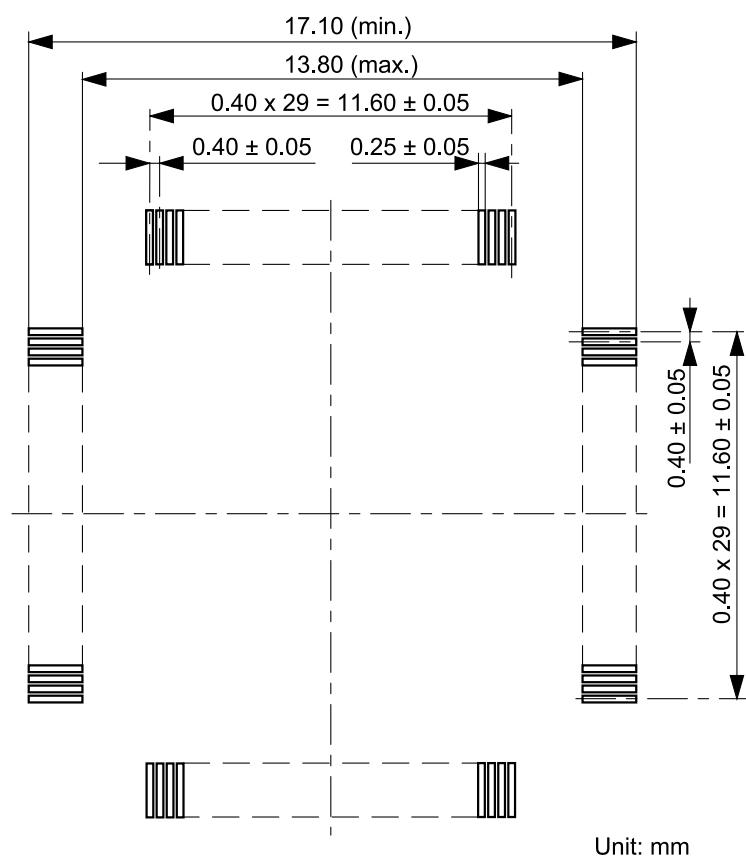
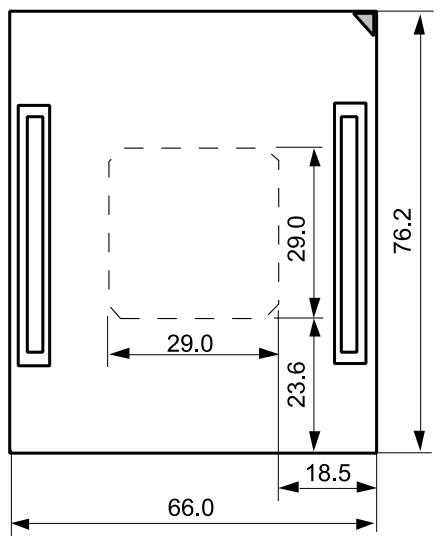


Figure 5 Recommended Dimensions for Mount Pad

2.4 Dimensions for User System Interface Cable Head

The dimensions for the user system interface cable head are shown in figure 6.



Unit: mm
Tolerance: ± 0.5 mm

Figure 6 Dimensions for User System Interface Cable Head

2.5 Resulting Dimensions after Connecting User System Interface Cable

The resulting dimensions, after connecting the user system interface cable head to the user system, are shown in figure 7.

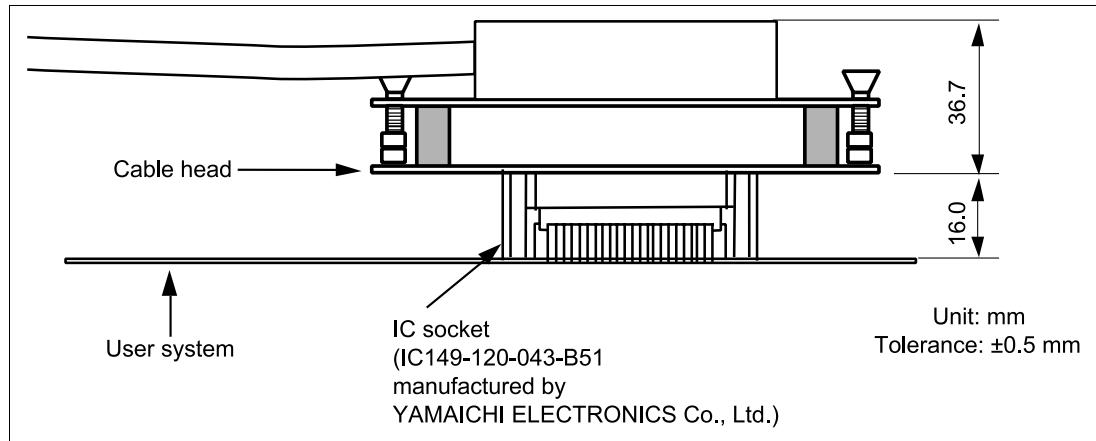


Figure 7 Resulting Dimensions after Connecting User System Interface Cable

Section 3 Installing the MCU to the User System

CAUTION

1. **Check the location of pin 1 before inserting.**
2. **Use a Philips-type screwdriver whose head matches the screw head.**
3. **The tightening torque must be 0.098 N•m or less.**
If the applied torque cannot be accurately measured, stop tightening when the force required to turn the screw becomes significantly greater than that needed when first tightening. If a screw is tightened too much, the screw head may break or an IC socket contact error may be caused by a crack in the IC socket solder.
4. **If the MCU does not operate correctly, cracks might have occurred in the solder. Check conduction with a tester and re-solder the IC socket if necessary.**

Check the location of pin 1 before inserting the MCU into the IC socket on the user system, as shown in figure 8. After inserting the MCU, fasten the socket cover with the provided four screws (M2 x 8 mm; with flat washers). Take special care, such as manually securing the IC socket soldered area, to prevent the IC socket from being damaged by overtightening the screws or twisting the components.

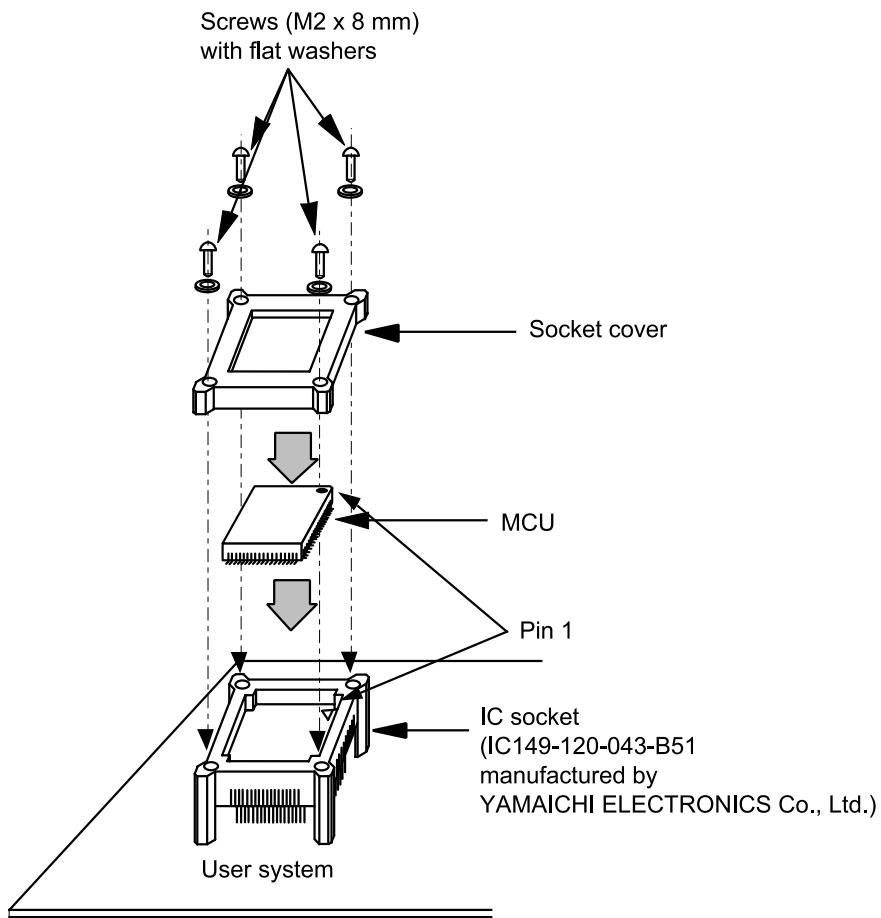


Figure 8 Installing MCU to User System

Section 4 Verifying Operation

- When using the E6000 emulator for the H8S/2368 series, turn on the emulator according to the procedures described in the H8S Series E6000 Emulator User's Manual (HS2000EPI61HE).
 - Verify the user system interface cable connections by accessing the external memory and ports to check the bus states of the pins with the **MEMORY_FILL** command (emulator command). If an error is detected, recheck the soldered IC socket and the location of pin 1.
 - The emulator connected to this user system interface cable supports two kinds of clock sources as the MCU clock: an emulator internal clock and an external clock on the user system. For details, refer to the Emulator Supplementary Information (HS2678REPI61HE).
 - To use the emulator internal clock
Select the clock in the emulator station as the system clock (ϕ), by using the **CLOCK** command (emulator command).
 - To use the external clock on the user system
Select target clock t or t2 with the **CLOCK** command (emulator command). Supply the external clock from the user system to the emulator by inputting the external clock from the EXTAL terminal on the cable head or connecting a crystal oscillator to the EXTAL and XTAL terminals. For details, refer to Clock Pulse Generator, in the H8S/2368 Series, Hardware Manual.
The user system interface cable has the oscillator circuits shown in figure 9.

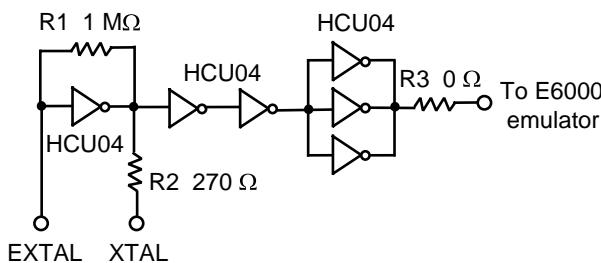


Figure 9 Clock Oscillator Circuits

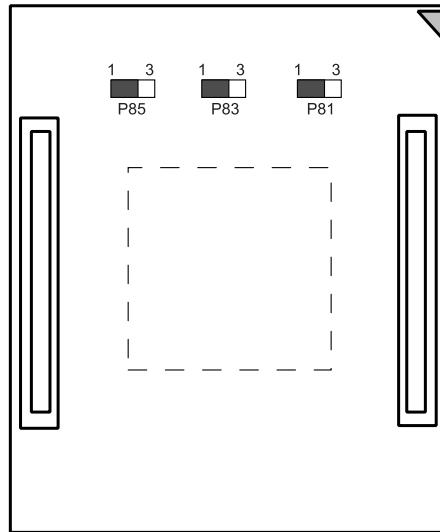
Section 5 Setting P81, P83, and P85 Jumper Sockets

This user system interface cable switches the P81, P83, and P85 jumper pins depending on the device type of the port function or RTC function version.

Figure 10 shows the setting of these jumper sockets.

CAUTION

Set the jumper sockets as shown in figure 10.



Device type	P81, P83, P85
Port function version	1-2 pins disconnected (setting at shipment)
RTC function version	2-3 pins disconnected

Figure 10 P81, P83, and P85 Jumper Sockets

Section 6 Notice

1. Make sure that pin 1 on the user system IC socket is correctly aligned with pin 1 on the cable head before inserting the cable head into the user system IC socket.
2. The dimensions of the recommended mount pad for the user system IC socket are different from those of the MCU.
3. This user system interface cable is specifically designed for the HS2678REPI61H emulator. Do not use this cable with any other emulator station.
4. To prevent breaking of wires in the cable body, do not place heavy or sharp metal objects on the user system interface cable.
5. While the emulator station is connected to the user system with the user system interface cable, force must not be applied to the cable head. Place the emulator station, user system interface cable, and user system as shown in the example in figure 11.

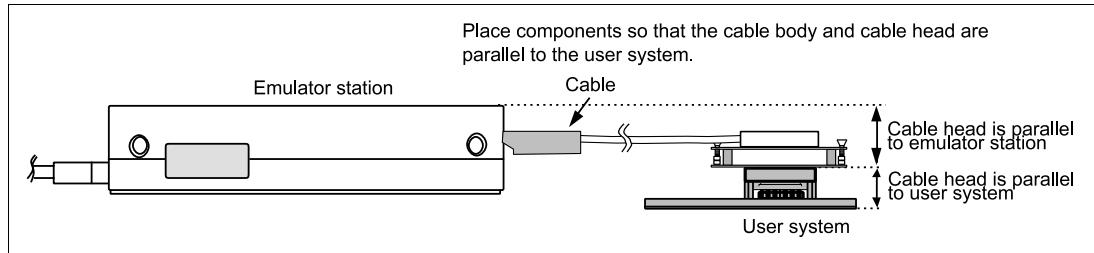


Figure 11 User System Interface Cable Location Example

6. The P1 jumper socket is used for testing. Do not remove the jumper pin inserted on pin 1 side.

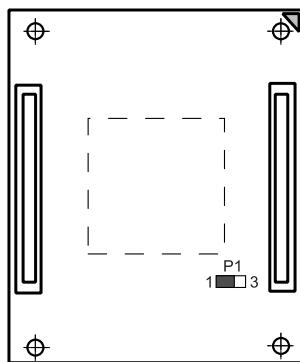


Figure 12 P1 Jumper Socket