

512K-Bit CMOS Flash Memory

Licensed Intel second source



FEATURES

- Fast Read Access Time: 90/120/150 ns
- **■** Low Power CMOS Dissipation:
 - -Active: 30 mA max (CMOS/TTL levels)
 - -Standby: 1 mA max (TTL levels)
 - -Standby: 100 µA max (CMOS levels)
- **■** High Speed Programming:
 - -10 µs per byte
 - -1 Sec Typ Chip Program
- 12.0V ± 5% Programming and Erase Voltage
- **■** Electronic Signature

- Commercial, Industrial and Automotive Temperature Ranges
- Stop Timer for Program/Erase
- On-Chip Address and Data Latches
- **JEDEC Standard Pinouts:**
 - -32-pin DIP
 - -32-pin PLCC
 - -32-pin TSOP (8 x 20)
- 100,000 Program/Erase Cycles
- 10 Year Data Retention
- "Green" Package Options Available

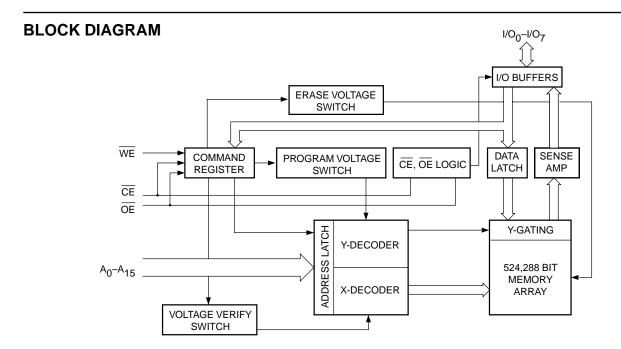
DESCRIPTION

The CAT28F512 is a high speed 64K x 8-bit electrically erasable and reprogrammable Flash memory ideally suited for applications requiring in-system or after-sale code updates. Electrical erasure of the full memory contents is achieved typically within 0.5 second.

It is pin and Read timing compatible with standard EPROM and EEPROM devices. Programming and Erase are performed through an operation and verify algorithm. The instructions are input via the I/O bus, using a

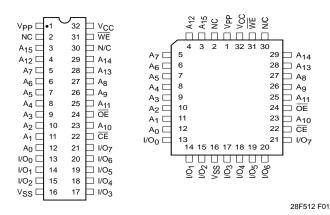
two write cycle scheme. Address and Data are latched to free the I/O bus and address bus during the write operation.

The CAT28F512 is manufactured using Catalyst's advanced CMOS floating gate technology. It is designed to endure 100,000 program/erase cycles and has a data retention of 10 years. The device is available in JEDEC approved 32-pin plastic DIP, 32-pin PLCC or 32-pin TSOP packages.



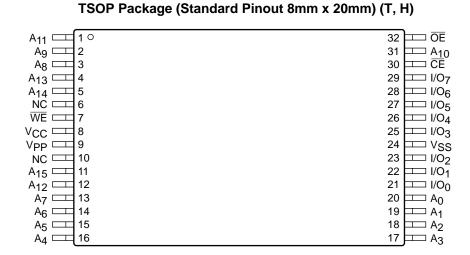
PIN CONFIGURATION

PLCC Package (N, G) DIP Package (L)

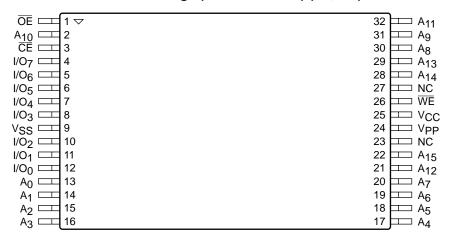


PIN FUNCTIONS

Pin Name	Туре	Function
A ₀ -A ₁₅	Input	Address Inputs for memory addressing
I/O ₀ –I/O ₇	I/O	Data Input/Output
CE	Input	Chip Enable
ŌĒ	Input	Output Enable
WE	Input	Write Enable
Vcc		Voltage Supply
Vss		Ground
VPP		Program/Erase Voltage Supply



TSOP Package (Reverse Pinout) (TR, HR)



28F512 F03

ABSOLUTE MAXIMUM RATINGS*

Temperature Under Bias55°C to +95°C
Storage Temperature65°C to +150°C
Voltage on Any Pin with Respect to Ground ⁽¹⁾ 2.0V to +V _{CC} + 2.0V
Voltage on Pin A ₉ with Respect to Ground ⁽¹⁾ 2.0V to +13.5V
V _{PP} with Respect to Ground during Program/Erase ⁽¹⁾ 2.0V to +14.0V
V_{CC} with Respect to $Ground^{(1)}$ –2.0V to +7.0V
Package Power Dissipation Capability (T _A = 25°C)
Lead Soldering Temperature (10 secs) 300°C
Output Short Circuit Current ⁽²⁾ 100 mA

*COMMENT

Stresses above those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions outside of those listed in the operational sections of this specification is not implied. Exposure to any absolute maximum rating for extended periods may affect device performance and reliability.

RELIABILITY CHARACTERISTICS

Symbol	Parameter	Min.	Max.	Units	Test Method
N _{END} (3)	Endurance	100K		Cycles/Byte	MIL-STD-883, Test Method 1033
T _{DR} ⁽³⁾	Data Retention	10		Years	MIL-STD-883, Test Method 1008
V _{ZAP} (3)	ESD Susceptibility	2000		Volts	MIL-STD-883, Test Method 3015
ILTH ⁽³⁾⁽⁴⁾	Latch-Up	100		mA	JEDEC Standard 17

CAPACITANCE $T_A = 25^{\circ}C$, f = 1.0 MHz

		Limits			
Symbol	Test	Min	Max.	Units	Conditions
C _{IN} (3)	Input Pin Capacitance		6	pF	$V_{IN} = 0V$
C _{OUT} (3)	Output Pin Capacitance		10	pF	V _{OUT} = 0V
C _{VPP} (3)	V _{PP} Supply Capacitance		25	pF	V _{PP} = 0V

- (1) The minimum DC input voltage is -0.5V. During transitions, inputs may undershoot to -2.0V for periods of less than 20 ns. Maximum DC voltage on output pins is V_{CC} +0.5V, which may overshoot to V_{CC} + 2.0V for periods of less than 20ns.
- (2) Output shorted for no more than one second. No more than one output shorted at a time.
- (3) This parameter is tested initially and after a design or process change that affects the parameter.
- (4) Latch-up protection is provided for stresses up to 100 mA on address and data pins from -1V to V_{CC} +1V.

D.C. OPERATING CHARACTERISTICS

 V_{CC} = +5V ±10%, unless otherwise specified.

			Limits		
Symbol	Parameter	Min.	Max.	Unit	Test Conditions
l _{LI}	Input Leakage Current		±1	μΑ	$V_{IN} = V_{CC} \text{ or } V_{SS}$ $V_{CC} = 5.5V, \overline{OE} = V_{IH}$
I _{LO}	Output Leakage Current		±1	μΑ	$V_{OUT} = V_{CC} \text{ or } V_{SS},$ $V_{CC} = 5.5V, \overline{OE} = V_{IH}$
I _{SB1}	V _{CC} Standby Current CMOS		100	μΑ	$\overline{\text{CE}} = \text{V}_{\text{CC}} \pm 0.5 \text{V},$ $\text{V}_{\text{CC}} = 5.5 \text{V}$
I _{SB2}	V _{CC} Standby Current TTL		1	mA	CE = V _{IH} , V _{CC} = 5.5V
I _{CC1}	V _{CC} Active Read Current		30	mA	$V_{CC} = 5.5V$, $\overline{CE} = V_{IL}$, $I_{OUT} = 0$ mA, $f = 6$ MHz
I _{CC2} ⁽¹⁾	V _{CC} Programming Current		15	mA	V _{CC} = 5.5V, Programming in Progress
I _{CC3} ⁽¹⁾	V _{CC} Erase Current		15	mA	V _{CC} = 5.5V, Erasure in Progress
I _{CC4} ⁽¹⁾	V _{CC} Prog./Erase Verify Current		15	mA	V _{CC} = 5.5V, Program or Erase Verify in Progress
I _{PPS}	V _{PP} Standby Current		±10	μΑ	V _{PP} = V _{PPL}
I _{PP1}	V _{PP} Read Current		200	μΑ	V _{PP} = V _{PPH}
I _{PP2} ⁽¹⁾	V _{PP} Programming Current		30	mA	V _{PP} = V _{PPH} , Programming in Progress
I _{PP3} ⁽¹⁾	V _{PP} Erase Current		30	mA	V _{PP} = V _{PPH} , Erasure in Progress
I _{PP4} ⁽¹⁾	V _{PP} Prog./Erase Verify Current		5	mA	V _{PP} = V _{PPH} , Program or Erase Verify in Progress
V _{IL}	Input Low Level TTL	-0.5	0.8	V	
V _{ILC}	Input Low Level CMOS	-0.5	0.8	V	
VoL	Output Low Level		0.45	V	$I_{OL} = 5.8 \text{mA}, V_{CC} = 4.5 \text{V}$
V _{IH}	Input High Level TTL	2	V _{CC} +0.5	V	
V _{IHC}	Input High Level CMOS	V _{CC} *0.7	V _{CC} +0.5	V	
V _{OH1}	Output High Level TTL	2.4		V	$I_{OH} = -2.5$ mA, $V_{CC} = 4.5$ V
V _{OH2}	Output High Level CMOS	V _{CC} -0.4		V	$I_{OH} = -400 \mu A, V_{CC} = 4.5 V$
V _{ID}	A ₉ Signature Voltage	11.4	13	V	$A_9 = V_{ID}$
I _{ID} ⁽¹⁾	A ₉ Signature Current		200	μΑ	$A_9 = V_{ID}$
V_{LO}	V _{CC} Erase/Prog. Lockout Voltage	2.5		V	

⁽¹⁾ This parameter is tested initially and after a design or process change that affects the parameter.

SUPPLY CHARACTERISTICS

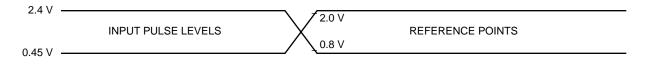
		Lin	nits	
Symbol	Parameter	Min	Max.	Unit
Vcc	V _{CC} Supply Voltage	4.5	5.5	V
V_{PPL}	V _{PP} During Read Operations	0	6.5	V
V _{PPH}	V _{PP} During Read/Erase/Program	11.4	12.6	V

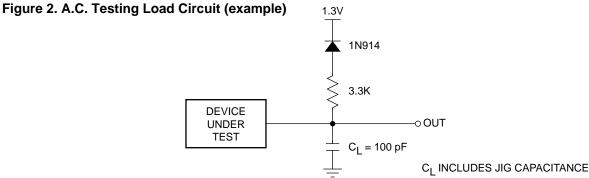
A.C. CHARACTERISTICS, Read Operation

 V_{CC} = +5V ±10%, unless otherwise specified.

JEDEC	Standard		28F512-90		28F5	12-12	2-12 28F512-15		
Symbol	Symbol	Parameter	Min.	Max.	Min.	Max.	Min.	Max.	Unit
t _{AVAV}	t _{RC}	Read Cycle Time	90		120		150		ns
t _{ELQV}	t _{CE}	CE Access Time		90		120		150	ns
t _{AVQV}	t _{ACC}	Address Access Time		90		120		150	ns
t _{GLQV}	toE	OE Access Time		35		50		55	ns
t _{AXQX}	tон	Output Hold from Address OE/CE Change	0		0		0		ns
t _{GLQX}	t _{OLZ} (1)(6)	OE to Output in Low-Z	0		0		0		ns
t _{ELQX}	t _{LZ} ⁽¹⁾⁽⁶⁾	CE to Output in Low-Z	0		0		0		ns
t _{GHQZ}	t _{DF} ⁽¹⁾⁽²⁾	OE High to Output High-Z		20		30		35	ns
t _{EHQZ}	t _{DF} ⁽¹⁾⁽²⁾	CE High to Output High-Z		30		40		45	ns
t _{WHGL} (1)	-	Write Recovery Time Before Read	6		6		6		μs

Figure 1. A.C. Testing Input/Output Waveform⁽³⁾⁽⁴⁾⁽⁵⁾





- (1) This parameter is tested initially and after a design or process change that affects the parameter.
- (2) Output floating (High-Z) is defined as the state where the external data line is no longer driven by the output buffer.
- (3) Input Rise and Fall Times (10% to 90%) < 10 ns.
- (4) Input Pulse Levels = 0.45V and 2.4V.
- (5) Input and Output Timing Reference = 0.8V and 2.0V.
- (6) Low-Z is defined as the state where the external data may be driven by the output buffer but may not be valid.

A.C. CHARACTERISTICS, Program/Erase Operation

 V_{CC} = +5V ±10%, unless otherwise specified.

JEDEC	Standard		28F512-90 28F512-12		12-12	28F5	12-15		
Symbol	Symbol	Parameter	Min.	Max.	Min.	Max.	Min.	Max.	Unit
t _{AVAV}	t _{WC}	Write Cycle Time	90		120		150		ns
t _{AVWL}	t _{AS}	Address Setup Time	0		0		0		ns
t _{WLAX}	t _{AH}	Address Hold Time	40		40		40		ns
t _{DVWH}	t _{DS}	Data Setup Time	40		40		40		ns
t _{WHDX}	t _{DH}	Data Hold Time	10		10		10		ns
t _{ELWL}	tcs	CE Setup Time	0		0		0		ns
t _{WHEH}	tсн	CE Hold Time	0		0		0		ns
t _{WLWH}	t _{WP}	WE Pulse Width	40		40		40		ns
t _{WHWL}	t _{WPH}	WE High Pulse Width	20		20		20		ns
t _{WHWH1} (2)	-	Program Pulse Width	10		10		10		μs
t _{WHWH2} (2)	-	Erase Pulse Width	9.5		9.5		9.5		ms
t _{WHGL}	-	Write Recovery Time Before Read	6		6		6		μs
t _{GHWL}	-	Read Recovery Time Before Write	0		0		0		μs
t _{VPEL}	-	V _{PP} Setup Time to $\overline{\text{CE}}$	100		100		100		ns

ERASE AND PROGRAMMING PERFORMANCE(1)

	28F512-90			2	28F512-12			28F512-15		
Parameter	Min.	Тур.	Max.	Min.	Тур.	Max.	Min.	Тур.	Max.	Unit
Chip Erase Time ⁽³⁾⁽⁵⁾		0.5	10		0.5	10		0.5	10	sec
Chip Program Time ⁽³⁾⁽⁴⁾		1	6		1	6		1	6	sec

- (1) Please refer to Supply characteristics for the value of V_{PPH} and V_{PPL} . The V_{PP} supply can be either hardwired or switched. If V_{PP} is switched, V_{PPL} can be ground, less than V_{CC} + 2.0V or a no connect with a resistor tied to ground.
- (2) Program and Erase operations are controlled by internal stop timers.
- (3) 'Typicals' are not guaranteed, but based on characterization data. Data taken at 25°C, 12.0V V_{PP}.
- (4) Minimum byte programming time (excluding system overhead) is 16 μs (10 μs program + 6 μs write recovery), while maximum is 400 μs/byte (16 μs x 25 loops). Max chip programming time is specified lower than the worst case allowed by the programming algorithm since most bytes program significantly faster than the worst case byte.
- (5) Excludes 00H Programming prior to Erasure.

FUNCTION TABLE(1)

			Pins			
Mode	CE	OE	WE	V _{PP}	I/O	Notes
Read	V _{IL}	VIL	V _{IH}	V _{PPL}	D _{OUT}	
Output Disable	V _{IL}	V _{IH}	V _{IH}	Х	High-Z	
Standby	V _{IH}	Х	Х	V _{PPL}	High-Z	
Signature (MFG)	VIL	VIL	V _{IH}	Х	31H	$A_0 = V_{IL}, A_9 = 12V$
Signature (Device)	VIL	VIL	V _{IH}	Х	B8H	$A_0 = V_{IH}, A_9 = 12V$
Program/Erase	VIL	V _{IH}	VIL	V _{PPH}	D _{IN}	See Command Table
Write Cycle	V _{IL}	V _{IH}	VIL	V _{PPH}	D _{IN}	During Write Cycle
Read Cycle	V _{IL}	VIL	V _{IH}	V _{PPH}	D _{OUT}	During Write Cycle

WRITE COMMAND TABLE

Commands are written into the command register in one or two write cycles. The command register can be altered only when V_{PP} is high and the instruction byte is latched on the rising edge of \overline{WE} . Write cycles also internally latch addresses and data required for programming and erase operations.

				Pins			
	Firs	t Bus Cycle					
Mode	Operation	Address	ddress D _{IN} Operation Add		Address	D _{IN}	D _{OUT}
Set Read	Write	Х	00H	Read	A _{IN}		D _{OUT}
Read Sig. (MFG)	Write	Х	90H	Read	00		31H
Read Sig. (Device)	Write	Х	90H	Read	01		В8Н
Erase	Write	Х	20H	Write	Х	20H	
Erase Verify	Write	A _{IN}	A0H	Read	Х		D _{OUT}
Program	Write	Х	40H	Write	A _{IN}	A _{IN} D _{IN}	
Program Verify	Write	Х	C0H	Read	Х		D _{OUT}
Reset	Write	Х	FFH	Write	Х	FFH	

⁽¹⁾ Logic Levels: X = Logic 'Do not care' (V_{IH} , V_{IL} , V_{PPL} , V_{PPH})

READ OPERATIONS

Read Mode

A Read operation is performed with both CE and $\overline{\text{OE}}$ low and with $\overline{\text{WE}}$ high. V_{PP} can be either high or low, however, if V_{PP} is high, the Set READ command has to be sent before reading data (see Write Operations). The data retrieved from the I/O pins reflects the contents of the memory location corresponding to the state of the 16 address pins. The respective timing waveforms for the read operation are shown in Figure 3. Refer to the AC Read characteristics for specific timing parameters.

Signature Mode

The signature mode allows the user to identify the IC manufacturer and the type of device while the device resides in the target system. This mode can be activated in either of two ways; through the conventional method of applying a high voltage (12V) to address pin A₉ or by sending an instruction to the command register (see Write Operations).

The conventional mode is entered as a regular READ mode by driving the \overline{CE} and \overline{OE} pins low (with \overline{WE} high), and applying the required high voltage on address pin A_9 while all other address lines are held at V_{IL} .

A Read cycle from address 0000H retrieves the binary code for the IC manufacturer on outputs I/O₀ to I/O₇:

CATALYST Code =
$$00110001$$
 (31H)

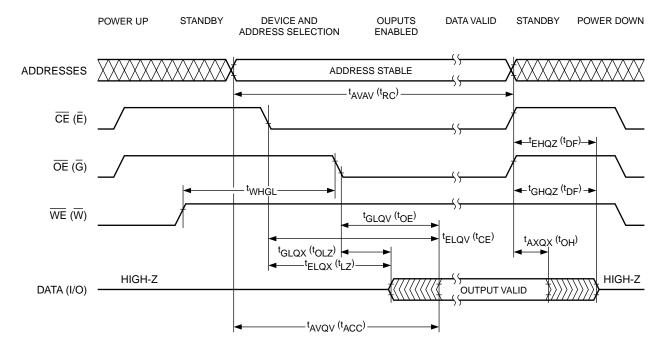
A Read cycle from address 0001H retrieves the binary code for the device on outputs I/O₀ to I/O₇.

28F512 Code = 1011 1000 (B8H)

Standby Mode

With CE at a logic-high level, the CAT28F512 is placed in a standby mode where most of the device circuitry is disabled, thereby substantially reducing power consumption. The outputs are placed in a high-impedance state.

Figure 3. A.C. Timing for Read Operation



WRITE OPERATIONS

The following operations are initiated by observing the sequence specified in the Write Command Table.

Read Mode

The device can be put into a standard READ mode by initiating a write cycle with 00H on the data bus. The subsequent read cycles will be performed similar to a standard EPROM or EEPROM Read.

Signature Mode

An alternative method for reading device signature (see Read Operations Signature Mode), is initiated by writing the code 90H into the command register while keeping VPP high. A read cycle from address 0000H with CE and OE low (and WE high) will output the device signature.

CATALYST Code =
$$00110001$$
 (31H)

A Read cycle from address 0001H retrieves the binary code for the device on outputs I/O₀ to I/O₇.

28F512 Code = 1011 1000 (B8H)

Erase Mode

During the first Write cycle, the command 20H is written into the command register. In order to commence the erase operation, the identical command of 20H has to be written again into the register. This two-step process ensures against accidental erasure of the memory contents. The final erase cycle will be stopped at the rising edge of \overline{WE} , at which time the Erase Verify command (A0H) is sent to the command register. During this cycle, the address to be verified is sent to the address bus and latched when \overline{WE} goes low. An integrated stop timer allows for automatic timing control over this operation, eliminating the need for a maximum erase timing specification. Refer to AC Characteristics (Program/Erase) for specific timing parameters.

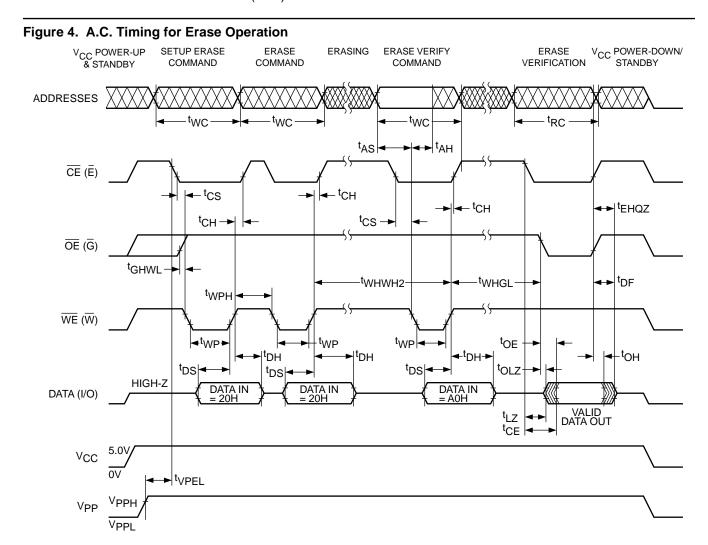
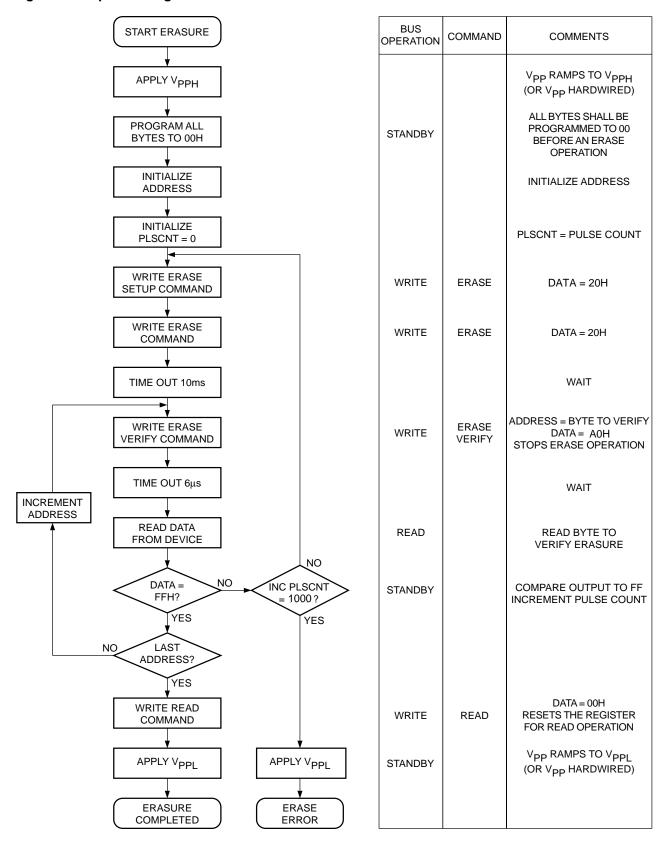


Figure 5. Chip Erase Algorithm⁽¹⁾



Note:

(1) The algorithm MUST BE FOLLOWED to ensure proper and reliable operation of the device.

Erase-Verify Mode

The Erase-verify operation is performed on every byte after each erase pulse to verify that the bits have been erased.

Programming Mode

The programming operation is initiated using the programming algorithm of Figure 7. During the first write cycle, the command 40H is written into the command register. During the second write cycle, the address of the memory location to be programmed is latched on the falling edge of \overline{WE} , while the data is latched on the rising edge of \overline{WE} . The program operation terminates with the next rising edge of \overline{WE} . An integrated stop timer allows for automatic timing control over this operation, eliminating the need for a maximum program timing specification. Refer to AC Characteristics (Program/Erase) for specific timing parameters.

Program-Verify Mode

A Program-verify cycle is performed to ensure that all bits have been correctly programmed following each byte programming operation. The specific address is already latched from the write cycle just completed, and stays latched until the verify is completed. The Program-verify operation is initiated by writing C0H into the command register. An internal reference generates the necessary high voltages so that the user does not need to modify V_{CC}. Refer to AC Characteristics (Program/ Erase) for specific timing parameters.

Figure 6. A.C. Timing for Programming Operation

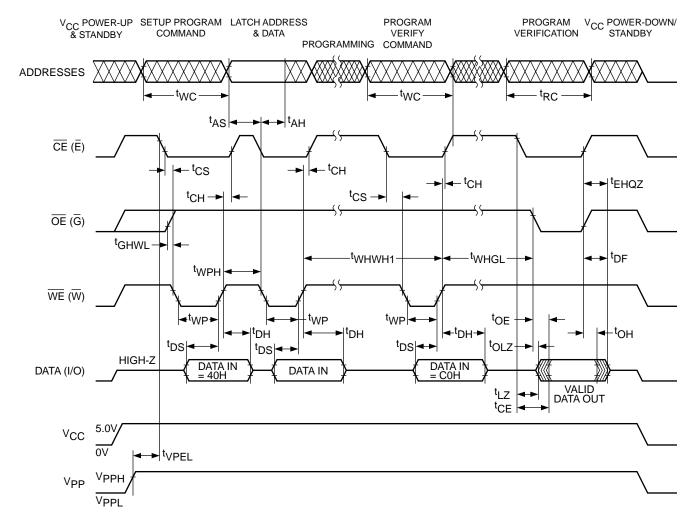
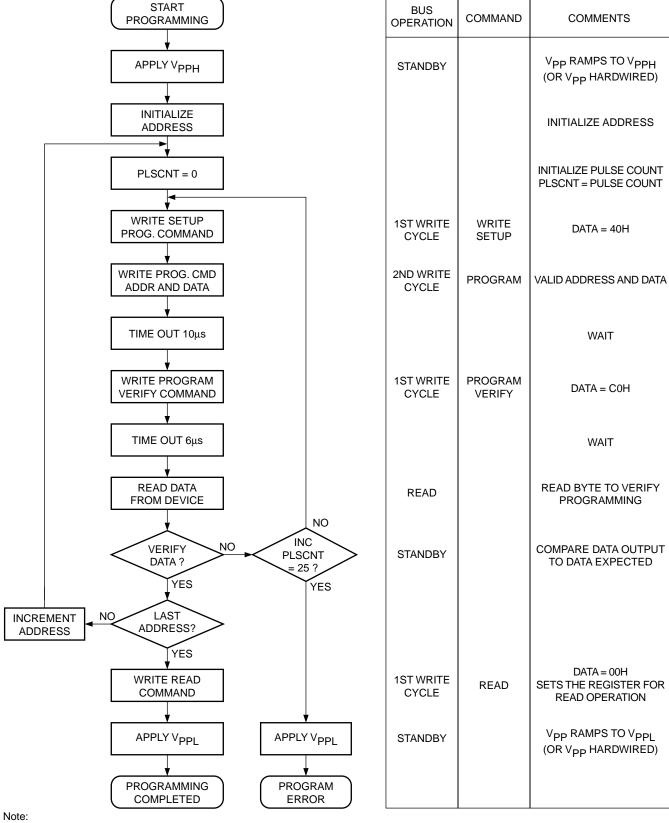


Figure 7. Programming Algorithm⁽¹⁾



⁽¹⁾ The algorithm MUST BE FOLLOWED to ensure proper and reliable operation of the device.

Abort/Reset

An Abort/Reset command is available to allow the user to safely abort an erase or program sequence. Two consecutive program cycles with FFH on the data bus will abort an erase or a program operation. The abort/reset operation can interrupt at any time in a program or erase operation and the device is reset to the Read Mode.

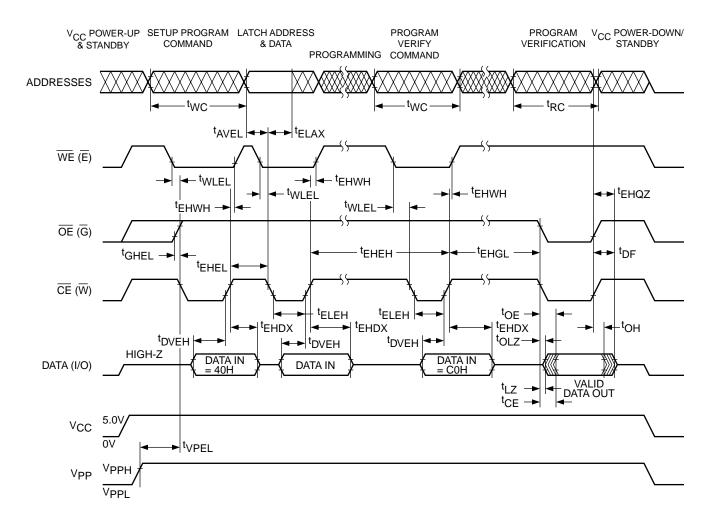
POWER SUPPLY DECOUPLING

To reduce the effect of transient power supply voltage spikes, it is good practice to use a $0.1\mu F$ ceramic capacitor between V_{CC} and V_{SS} and V_{PP} and V_{SS} . These high-frequency capacitors should be placed as close as possible to the device for optimum decoupling.

POWER UP/DOWN PROTECTION

The CAT28F512 offers protection against inadvertent programming during V_{PP} and V_{CC} power transitions. When powering up the device there is no power-on sequencing necessary. In other words, V_{PP} and V_{CC} may power up in any order. Additionally V_{PP} may be hardwired to V_{PPH} independent of the state of V_{CC} and any power up/down cycling. The internal command register of the CAT28F512 is reset to the Read Mode on power up.

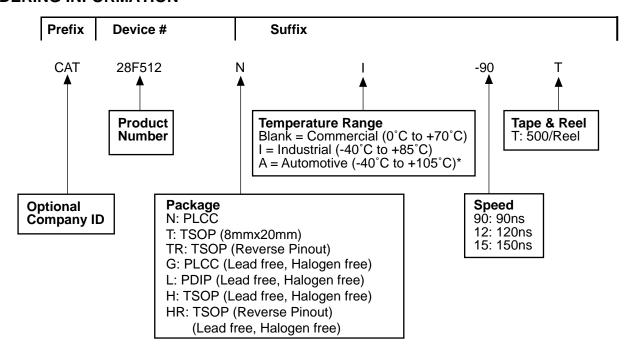
Figure 8. Alternate A.C. Timing for Program Operation



ALTERNATE CE-CONTROLLED WRITES

JEDEC	Standard		28F5	12-90	28F5	12-12	28F512-15		
Symbol	Symbol	Parameter	Min.	Max.	Min.	Max.	Min.	Max.	Unit
t _{AVAV}	t _{WC}	Write Cycle Time	90		120		120		ns
tavel	t _{AS}	Address Setup Time	0		0		0		ns
t _{ELAX}	t _{AH}	Address Hold Time	40		40		40		ns
t _{DVEH}	t _{DS}	Data Setup Time	40		40		40		ns
t _{EHDX}	t _{DH}	Data Hold Time	10		10		10		ns
t _{EHGL}	-	Write Recovery Time Before Read	6		6		6		μs
tGHEL	-	Read Recovery Time Before Write	0		0		0		μs
twlel	t _{WS}	WE Setup Time Before CE	0		0		0		ns
t _{EHWH}	-	WE Hold Time After CE	0		0		0		ns
t _{ELEH}	t _{CP}	Write Pulse Width	40		40		40		ns
t _{EHEL}	t _{CPH}	Write Pulse Width High	20		20		20		ns
t _{VPEL}	-	V _{PP} Setup Time to CE Low	100		100		100		ns

ORDERING INFORMATION



^{* -40°}C to +125°C is available upon request

Notes:

(1) The device used in the above example is a CAT28F512NI-90T (PLCC, Industrial Temperature, 90ns Access Time, Tape & Reel)

REVISION HISTORY

Date	Revision	Description
20-Apr-04	G	Added Green packages in all areas.
		Delete data sheet designation
		Update Features
		Update Description
		Update Pin Configuration
		Update Write Operations
		Update Ordering Information
		Update Revision History
		Update Rev Number
02-Jul-04	Н	Update Ordering Information
15-Oct-08	I	Eliminate PDIP SnPb package.
17-Nov-08	J	Change logo and fine print to ON Semiconductor

ON Semiconductor and are registered trademarks of Semiconductor Components Industries, LLC (SCILLC). SCILLC reserves the right to make changes without further notice to any products herein. SCILLC makes no warranty, representation or guarantee regarding the suitability of its products for any particular purpose, nor does SCILLC assume any liability arising out of the application or use of any product or circuit, and specifically disclaims any and all liability, including without limitation special, consequential or incidental damages. "Typical" parameters which may be provided in SCILLC data sheets and/or specifications can and do vary in different applications and actual performance may vary over time. All operating parameters, including "Typicals" must be validated for each customer application by customer's technical experts. SCILLC does not convey any license under its patent rights nor the rights of others. SCILLC products are not designed, intended, or authorized for use as components in systems intended for surgical implant into the body, or other applications intended to support or sustain life, or for any other application in which the failure of the SCILLC product could create a situation where personal injury or death may occur. Should Buyer purchase or use SCILLC products for any such unintended or unauthorized application, Buyer shall indemnify and hold SCILLC and its officers, employees, subsidiaries, affiliates, and distributors harmless against all claims, costs, damages, and expenses, and reasonable attorney fees arising out of, directly or indirectly, any claim of personal injury or death associated with such unintended or unauthorized use, even if such claim alleges that SCILLC was negligent regarding the design or manufacture of the part. SCILLC is an Equal Opportunity/Affirmative Action Employer. This literature is subject to all applicable copyright laws and is not for resale in any manner.

PUBLICATION ORDERING INFORMATION

LITERATURE FULFILLMENT:

Literature Distribution Center for ON Semiconductor P.O. Box 5163, Denver, Colorado 80217 USA Phone: 303-675-2175 or 800-344-3860 Toll Free USA/Canada Fax: 303-675-2176 or 800-344-3867 Toll Free USA/Canada Email: orderlit@onsemi.com N. American Technical Support: 800-282-9855 Toll Free USA/Canada

Europe, Middle East and Africa Technical Support: Phone: 421 33 790 2910

Japan Customer Focus Center: Phone: 81-3-5773-3850 ON Semiconductor Website: www.onsemi.com

Order Literature: http://www.onsemi.com/orderlit

For additional information, please contact your local Sales Representative