

SG3525A

Pulse Width Modulator Control Circuit

The SG3525A pulse width modulator control circuit offers improved performance and lower external parts count when implemented for controlling all types of switching power supplies. The on-chip +5.1 V reference is trimmed to $\pm 1\%$ and the error amplifier has an input common-mode voltage range that includes the reference voltage, thus eliminating the need for external divider resistors. A sync input to the oscillator enables multiple units to be slaved or a single unit to be synchronized to an external system clock. A wide range of deadtime can be programmed by a single resistor connected between the C_T and Discharge pins. This device also features built-in soft-start circuitry, requiring only an external timing capacitor. A shutdown pin controls both the soft-start circuitry and the output stages, providing instantaneous turn off through the PWM latch with pulsed shutdown, as well as soft-start recycle with longer shutdown commands. The under voltage lockout inhibits the outputs and the changing of the soft-start capacitor when V_{CC} is below nominal. The output stages are totem-pole design capable of sinking and sourcing in excess of 200 mA. The output stage of the SG3525A features NOR logic resulting in a low output for an off-state.

- 8.0 V to 35 V Operation
- 5.1 V $\pm 1.0\%$ Trimmed Reference
- 100 Hz to 400 kHz Oscillator Range
- Separate Oscillator Sync Pin
- Adjustable Deadtime Control
- Input Undervoltage Lockout
- Latching PWM to Prevent Multiple Pulses
- Pulse-by-Pulse Shutdown
- Dual Source/Sink Outputs: ± 400 mA Peak

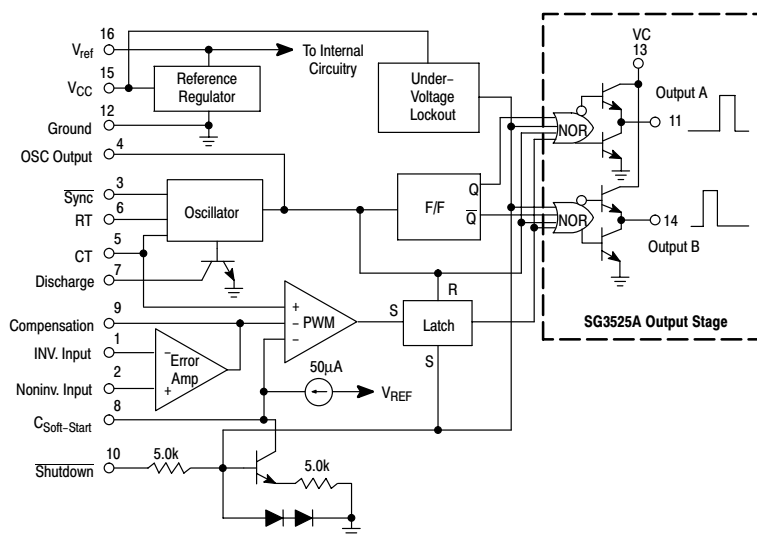


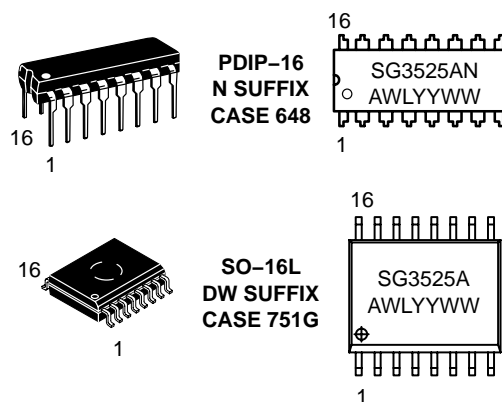
Figure 1. Representative Block Diagram



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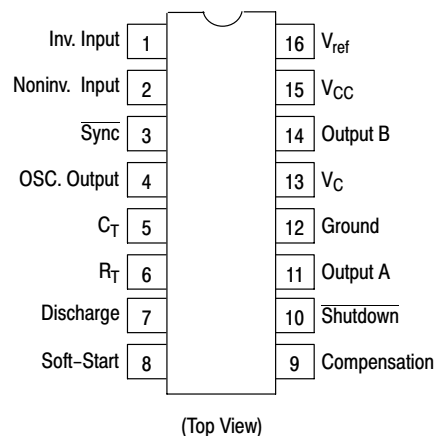
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MARKING DIAGRAMS



A = Assembly Location
WL = Wafer Lot
YY = Year
WW = Work Week

PIN CONNECTIONS



ORDERING INFORMATION

Device	Package	Shipping
SG3525AN	PDIP-16	25 Units/Rail
SG3525ADW	SO-16L	47 Units/Rail
SG3525ADWR2	SO-16L	1000 Tape & Reel

MAXIMUM RATINGS (Note 1)

Rating	Symbol	Value	Unit
Supply Voltage	V_{CC}	+40	Vdc
Collector Supply Voltage	V_C	+40	Vdc
Logic Inputs		-0.3 to +5.5	V
Analog Inputs		-0.3 to V_{CC}	V
Output Current, Source or Sink	I_O	±500	mA
Reference Output Current	I_{ref}	50	mA
Oscillator Charging Current		5.0	mA
Power Dissipation $T_A = +25^{\circ}\text{C}$ (Note 2) $T_C = +25^{\circ}\text{C}$ (Note 3)	P_D	1000 2000	mW
Thermal Resistance Junction-to-Air	$R_{\theta JA}$	100	$^{\circ}\text{C}/\text{W}$
Thermal Resistance Junction-to-Case	$R_{\theta JC}$	60	$^{\circ}\text{C}/\text{W}$
Operating Junction Temperature	T_J	+150	$^{\circ}\text{C}$
Storage Temperature Range	T_{stg}	-55 to +125	$^{\circ}\text{C}$
Lead Temperature (Soldering, 10 seconds)	T_{Solder}	+300	$^{\circ}\text{C}$

RECOMMENDED OPERATING CONDITIONS

Characteristics	Symbol	Min	Max	Unit
Supply Voltage	V_{CC}	8.0	35	Vdc
Collector Supply Voltage	V_C	4.5	35	Vdc
Output Sink/Source Current (Steady State) (Peak)	I_O	0 0	±100 ±400	mA
Reference Load Current	I_{ref}	0	20	mA
Oscillator Frequency Range	f_{osc}	0.1	400	kHz
Oscillator Timing Resistor	R_T	2.0	150	k Ω
Oscillator Timing Capacitor	C_T	0.001	0.2	μF
Deadtime Resistor Range	R_D	0	500	Ω
Operating Ambient Temperature Range	T_A	0	+70	$^{\circ}\text{C}$

1. Values beyond which damage may occur.
2. Derate at 10 mW/ $^{\circ}\text{C}$ for ambient temperatures above +50 $^{\circ}\text{C}$.
3. Derate at 16 mW/ $^{\circ}\text{C}$ for case temperatures above +25 $^{\circ}\text{C}$.

APPLICATION INFORMATION**Shutdown Options** (See Block Diagram, front page)

Since both the compensation and soft-start terminals (Pins 9 and 8) have current source pull-ups, either can readily accept a pull-down signal which only has to sink a maximum of 100 μA to turn off the outputs. This is subject to the added requirement of discharging whatever external capacitance may be attached to these pins.

An alternate approach is the use of the shutdown circuitry of Pin 10 which has been improved to enhance the available shutdown options. Activating this circuit by applying a positive signal on Pin 10 performs two functions: the PWM

latch is immediately set providing the fastest turn-off signal to the outputs; and a 150 μA current sink begins to discharge the external soft-start capacitor. If the shutdown command is short, the PWM signal is terminated without significant discharge of the soft-start capacitor, thus, allowing, for example, a convenient implementation of pulse-by-pulse current limiting. Holding Pin 10 high for a longer duration, however, will ultimately discharge this external capacitor, recycling slow turn-on upon release.

Pin 10 should not be left floating as noise pickup could conceivably interrupt normal operation.

ELECTRICAL CHARACTERISTICS ($V_{CC} = +20\text{ Vdc}$, $T_A = T_{low}$ to T_{high} [Note 4], unless otherwise noted.)

Characteristics	Symbol	Min	Typ	Max	Unit
REFERENCE SECTION					
Reference Output Voltage ($T_J = +25^\circ\text{C}$)	V_{ref}	5.00	5.10	5.20	Vdc
Line Regulation ($+8.0\text{ V} \leq V_{CC} \leq +35\text{ V}$)	Reg_{line}	–	10	20	mV
Load Regulation ($0\text{ mA} \leq I_L \leq 20\text{ mA}$)	Reg_{load}	–	20	50	mV
Temperature Stability	$\Delta V_{ref}/\Delta T$	–	20	–	mV
Total Output Variation Includes Line and Load Regulation over Temperature	ΔV_{ref}	4.95	–	5.25	Vdc
Short Circuit Current ($V_{ref} = 0\text{ V}$, $T_J = +25^\circ\text{C}$)	I_{SC}	–	80	100	mA
Output Noise Voltage ($10\text{ Hz} \leq f \leq 10\text{ kHz}$, $T_J = +25^\circ\text{C}$)	V_n	–	40	200	μV_{rms}
Long Term Stability ($T_J = +125^\circ\text{C}$) (Note 5)	S	–	20	50	mV/khr

OSCILLATOR SECTION (Note 6, unless otherwise noted.)

Initial Accuracy ($T_J = +25^\circ\text{C}$)		–	± 2.0	± 6.0	%
Frequency Stability with Voltage ($+8.0\text{ V} \leq V_{CC} \leq +35\text{ V}$)	$\frac{\Delta f_{osc}}{\Delta V_{CC}}$	–	± 1.0	± 2.0	%
Frequency Stability with Temperature	$\frac{\Delta f_{osc}}{\Delta T}$	–	± 0.3	–	%
Minimum Frequency ($R_T = 150\text{ k}\Omega$, $C_T = 0.2\text{ }\mu\text{F}$)	f_{min}	–	50	–	Hz
Maximum Frequency ($R_T = 2.0\text{ k}\Omega$, $C_T = 1.0\text{ nF}$)	f_{max}	400	–	–	kHz
Current Mirror ($I_{RT} = 2.0\text{ mA}$)		1.7	2.0	2.2	mA
Clock Amplitude		3.0	3.5	–	V
Clock Width ($T_J = +25^\circ\text{C}$)		0.3	0.5	1.0	μs
Sync Threshold		1.2	2.0	2.8	V
Sync Input Current (Sync Voltage = +3.5 V)		–	1.0	2.5	mA

ERROR AMPLIFIER SECTION ($V_{CM} = +5.1\text{ V}$)

Input Offset Voltage	V_{IO}	–	2.0	10	mV
Input Bias Current	I_{IB}	–	1.0	10	μA
Input Offset Current	I_{IO}	–	–	1.0	μA
DC Open Loop Gain ($R_L \geq 10\text{ M}\Omega$)	A_{VOL}	60	75	–	dB
Low Level Output Voltage	V_{OL}	–	0.2	0.5	V
High Level Output Voltage	V_{OH}	3.8	5.6	–	V
Common Mode Rejection Ratio ($+1.5\text{ V} \leq V_{CM} \leq +5.2\text{ V}$)	CMRR	60	75	–	dB
Power Supply Rejection Ratio ($+8.0\text{ V} \leq V_{CC} \leq +35\text{ V}$)	PSRR	50	60	–	dB

PWM COMPARATOR SECTION

Minimum Duty Cycle	DC_{min}	–	–	0	%
Maximum Duty Cycle	DC_{max}	45	49	–	%
Input Threshold, Zero Duty Cycle (Note 6)	V_{th}	0.6	0.9	–	V
Input Threshold, Maximum Duty Cycle (Note 6)	V_{th}	–	3.3	3.6	V
Input Bias Current	I_{IB}	–	0.05	1.0	μA

4. $T_{low} = 0^\circ$ $T_{high} = +70^\circ\text{C}$

5. Since long term stability cannot be measured on each device before shipment, this specification is an engineering estimate of average stability from lot to lot.

6. Tested at $f_{osc} = 40\text{ kHz}$ ($R_T = 3.6\text{ k}\Omega$, $C_T = 0.01\text{ }\mu\text{F}$, $R_D = 0\text{ }\Omega$).

ELECTRICAL CHARACTERISTICS (continued)

Characteristics	Symbol	Min	Typ	Max	Unit
SOFT-START SECTION					
Soft-Start Current ($V_{\text{shutdown}} = 0 \text{ V}$)		25	50	80	μA
Soft-Start Voltage ($V_{\text{shutdown}} = 2.0 \text{ V}$)		–	0.4	0.6	V
Shutdown Input Current ($V_{\text{shutdown}} = 2.5 \text{ V}$)		–	0.4	1.0	mA
OUTPUT DRIVERS (Each Output, $V_{\text{CC}} = +20 \text{ V}$)					
Output Low Level ($I_{\text{sink}} = 20 \text{ mA}$) ($I_{\text{sink}} = 100 \text{ mA}$)	V_{OL}	– –	0.2 1.0	0.4 2.0	V
Output High Level ($I_{\text{source}} = 20 \text{ mA}$) ($I_{\text{source}} = 100 \text{ mA}$)	V_{OH}	18 17	19 18	– –	V
Under Voltage Lockout (V_8 and $V_9 = \text{High}$)	V_{UL}	6.0	7.0	8.0	V
Collector Leakage, $V_{\text{C}} = +35 \text{ V}$ (Note 7)	$I_{\text{C(Leak)}}$	–	–	200	μA
Rise Time ($C_{\text{L}} = 1.0 \text{ nF}$, $T_{\text{J}} = 25^\circ\text{C}$)	t_{r}	–	100	600	ns
Fall Time ($C_{\text{L}} = 1.0 \text{ nF}$, $T_{\text{J}} = 25^\circ\text{C}$)	t_{f}	–	50	300	ns
Shutdown Delay ($V_{\text{DS}} = +3.0 \text{ V}$, $C_{\text{S}} = 0$, $T_{\text{J}} = +25^\circ\text{C}$)	t_{ds}	–	0.2	0.5	μs
Supply Current ($V_{\text{CC}} = +35 \text{ V}$)	I_{CC}	–	14	20	mA

7. Applies to SG3525A only, due to polarity of output pulses.

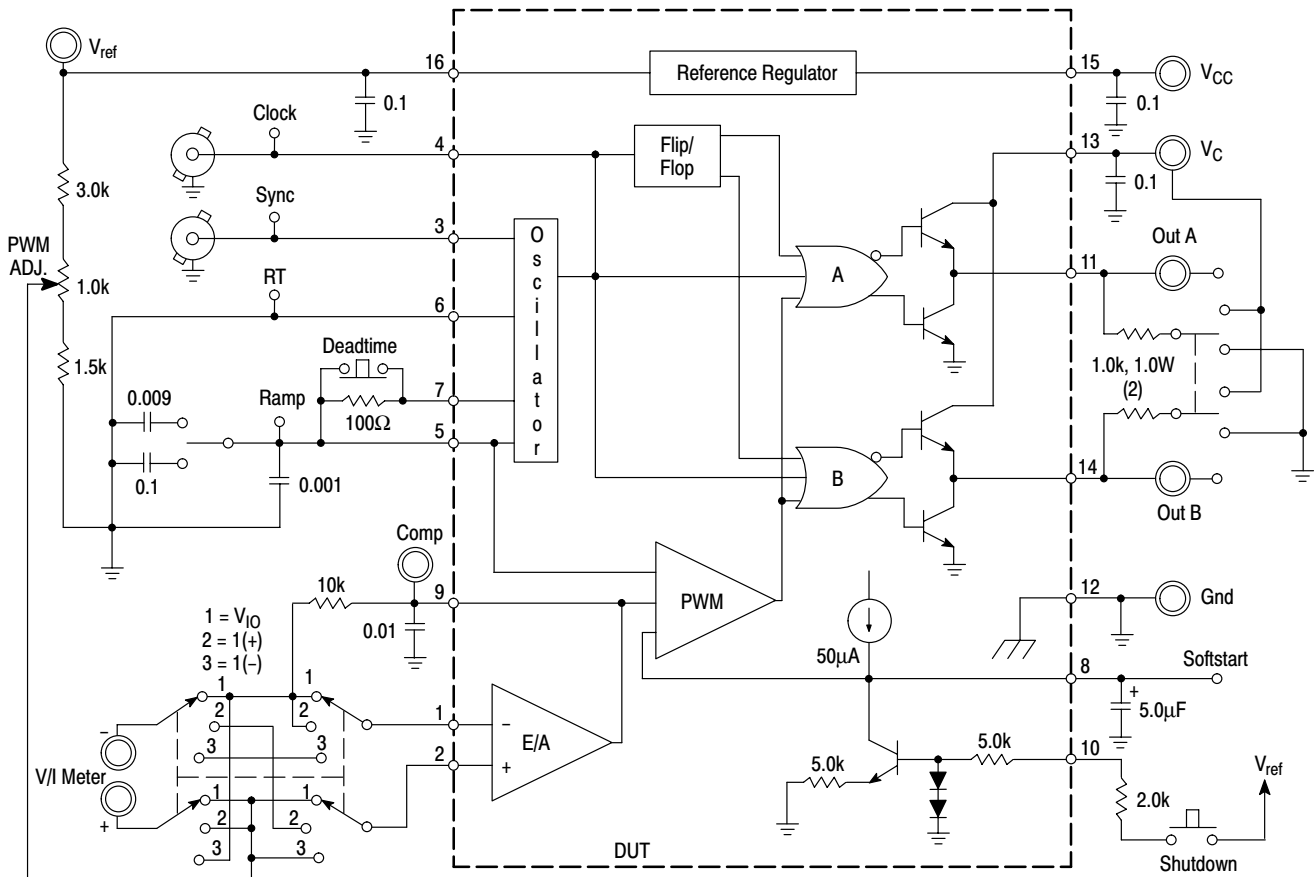


Figure 2. Lab Test Fixture

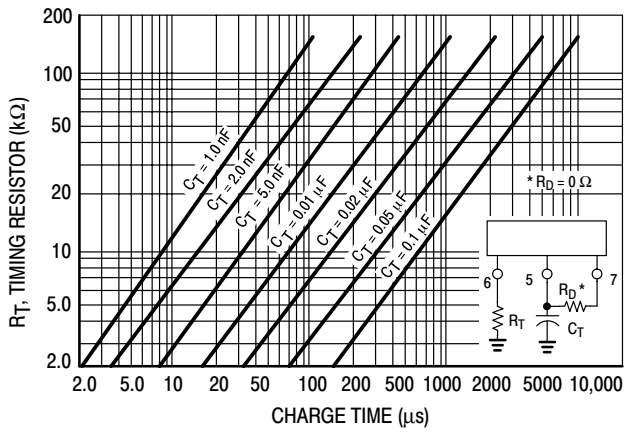


Figure 3. Oscillator Charge Time versus R_T

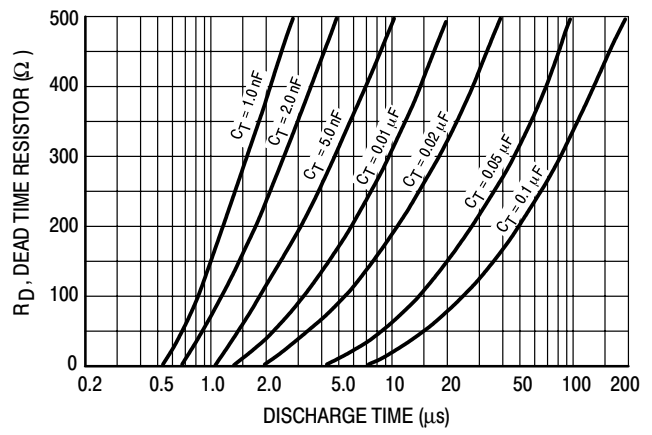


Figure 4. Oscillator Discharge Time versus R_D

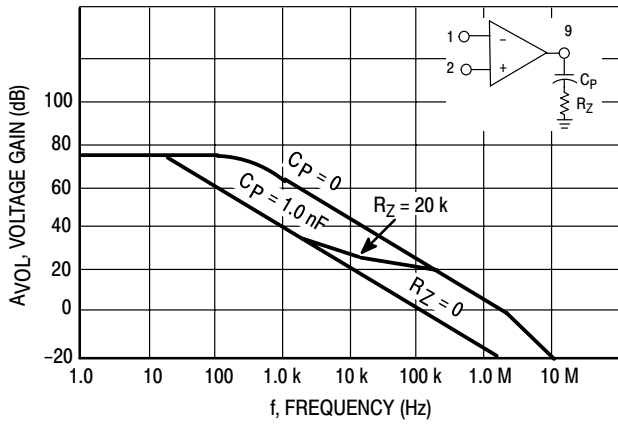


Figure 5. Error Amplifier Open Loop Frequency Response

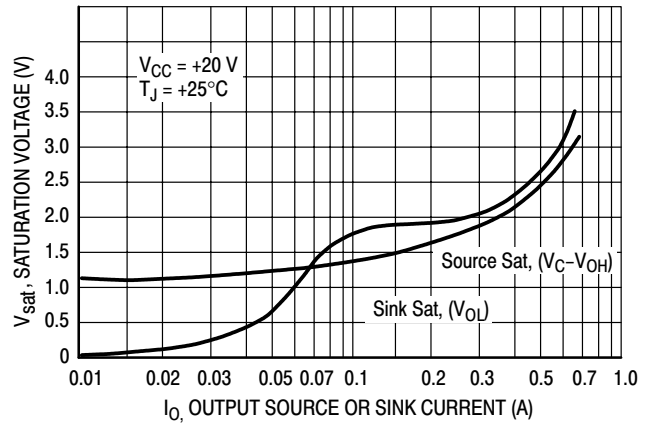


Figure 6. Output Saturation Characteristics

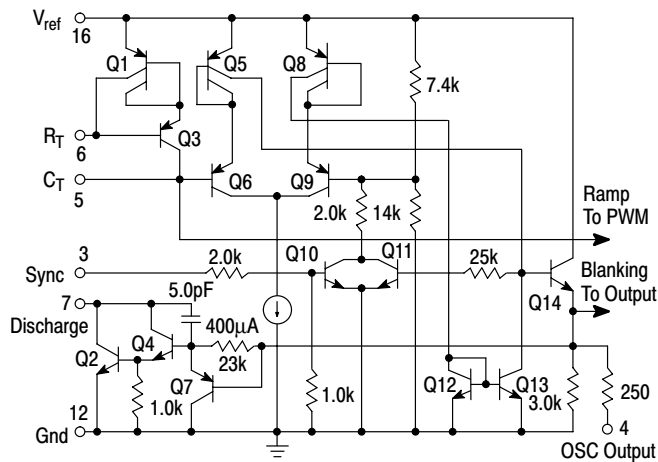


Figure 7. Oscillator Schematic

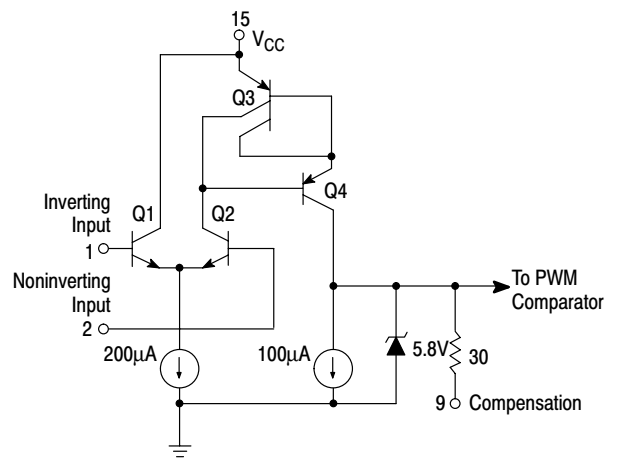


Figure 8. Error Amplifier Schematic

SG3525A

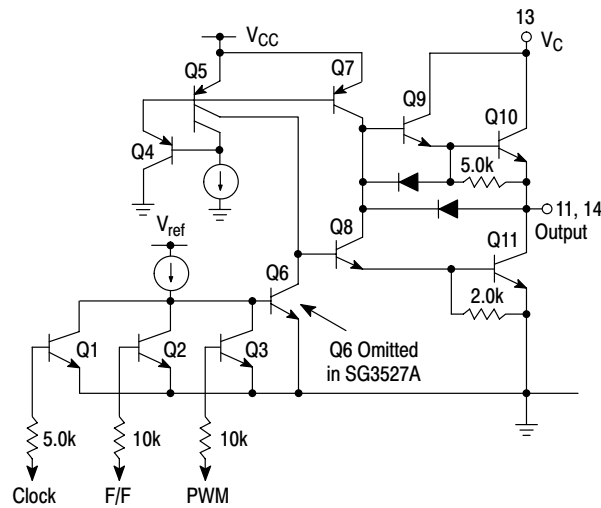
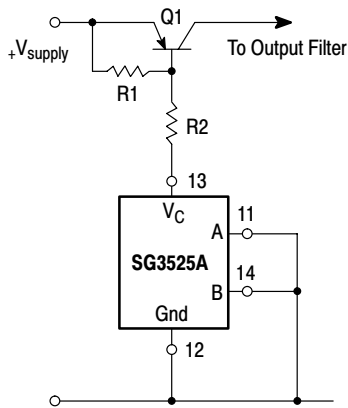
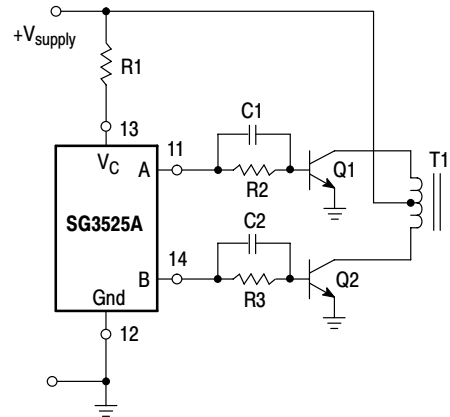


Figure 9. Output Circuit
(1/2 Circuit Shown)



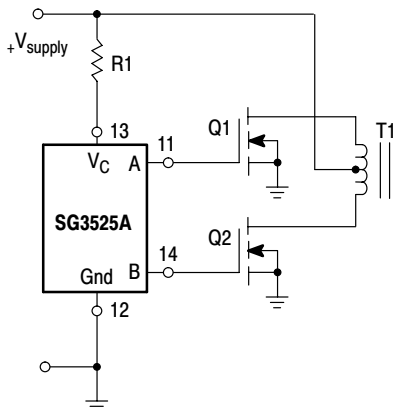
For single-ended supplies, the driver outputs are grounded. The V_C terminal is switched to ground by the totem-pole source transistors on alternate oscillator cycles.

Figure 10. Single-Ended Supply



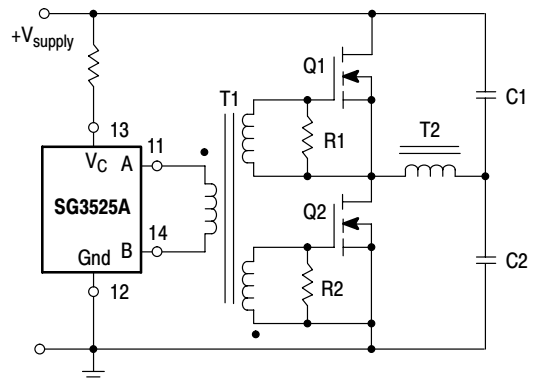
In conventional push-pull bipolar designs, forward base drive is controlled by R1-R3. Rapid turn-off times for the power devices are achieved with speed-up capacitors C1 and C2.

Figure 11. Push-Pull Configuration



The low source impedance of the output drivers provides rapid charging of power FET input capacitance while minimizing external components.

Figure 12. Driving Power FETS



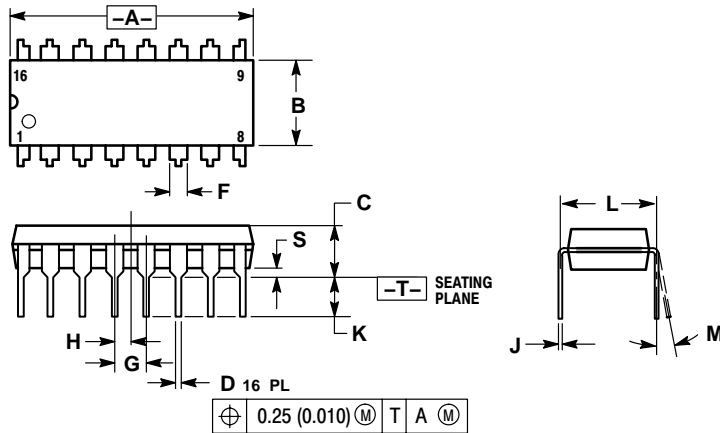
Low power transformers can be driven directly by the SG3525A. Automatic reset occurs during deadtime, when both ends of the primary winding are switched to ground.

Figure 13. Driving Transformers in a Half-Bridge Configuration

SG3525A

PACKAGE DIMENSIONS

PDIP-16
N SUFFIX
CASE 648-08
ISSUE R

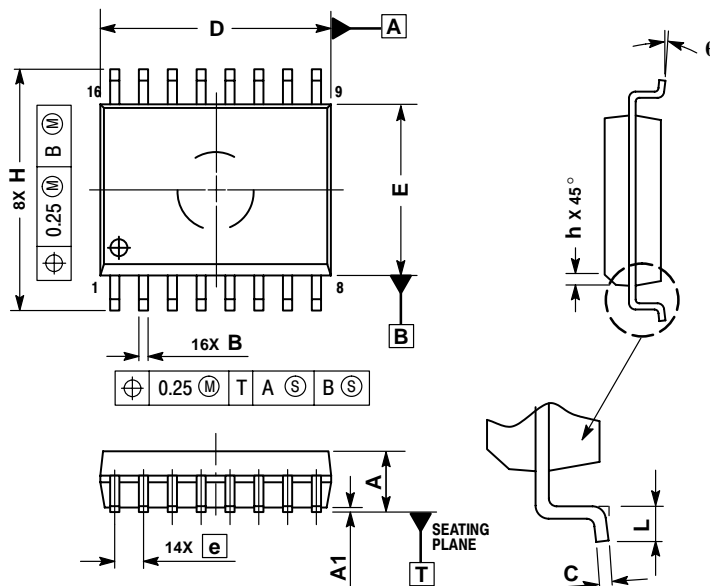


NOTES:

1. DIMENSIONING AND TOLERANCING PER ANSI Y14.5M, 1982.
2. CONTROLLING DIMENSION: INCH.
3. DIMENSION L TO CENTER OF LEADS WHEN FORMED PARALLEL.
4. DIMENSION B DOES NOT INCLUDE MOLD FLASH.
5. ROUNDED CORNERS OPTIONAL.

DIM	INCHES		MILLIMETERS	
	MIN	MAX	MIN	MAX
A	0.740	0.770	18.80	19.55
B	0.250	0.270	6.35	6.85
C	0.145	0.175	3.69	4.44
D	0.015	0.021	0.39	0.53
F	0.040	0.70	1.02	1.77
G	0.100 BSC		2.54 BSC	
H	0.050 BSC		1.27 BSC	
J	0.008	0.015	0.21	0.38
K	0.110	0.130	2.80	3.30
L	0.295	0.305	7.50	7.74
M	0°	10°	0°	10°
S	0.020	0.040	0.51	1.01


SO-16L
DW SUFFIX
CASE 751G-03
ISSUE B



NOTES:

1. DIMENSIONS ARE IN MILLIMETERS.
2. INTERPRET DIMENSIONS AND TOLERANCES PER ASME Y14.5M, 1994.
3. DIMENSIONS D AND E DO NOT INCLUDE MOLD PROTRUSION.
4. MAXIMUM MOLD PROTRUSION 0.15 PER SIDE.
5. DIMENSION B DOES NOT INCLUDE DAMBAR PROTRUSION. ALLOWABLE DAMBAR PROTRUSION SHALL BE 0.13 TOTAL IN EXCESS OF THE B DIMENSION AT MAXIMUM MATERIAL CONDITION.

DIM	MILLIMETERS	
	MIN	MAX
A	2.35	2.65
A1	0.10	0.25
B	0.35	0.49
C	0.23	0.32
D	10.15	10.45
E	7.40	7.60
e	1.27 BSC	
H	10.05	10.55
h	0.25	0.75
L	0.50	0.90
theta	0°	7°

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