



TIMER1 MODULE

Timer1 Module Data Sheet Errata

Clarifications/Corrections to the Data Sheet:

In the Device data sheets listed below, the following clarifications and corrections should be noted. Any silicon issues related to the Timer1 Module will be reported in a separate silicon errata. Please check the Microchip web site for any existing issues.

Device	Data Sheet	Device	Data Sheet	Device	Data Sheet	Device	Data Sheet	
PIC12F609	DS41302	PIC16F716	DS41206	PIC18F2321	DS39689	PIC18F6585	DS30491	
PIC12HV609		PIC16F737	DS30498	PIC18F4321		PIC18F6680		
PIC12F615		PIC16F747		PIC18F2331	PIC18F8585			
PIC12HV615		PIC16F767		PIC18F2431	PIC18F8680			
PIC12F629	DS41190	PIC16F777	DS41249	PIC18F4331	DS39616	PIC18F24J10	DS39682	
PIC12F675		PIC16F785		PIC18F4431		PIC18F25J10		
PIC12F635	DS41232	PIC16HV785	DS39598	PIC18F2439	DS30485	PIC18F44J10		DS39774
PIC16F636		PIC16F818		PIC18F2539		PIC18F45J10		
PIC16F639		PIC16F819	PIC18F4439	PIC18F63J11				
PIC12F683	DS41211	PIC16F870	DS30569	PIC18F4539	DS39632	PIC18F64J11	DS39770	
PIC14000	DS40122	PIC16F871		PIC18F2455		PIC18F65J11		
PIC16C62A	DS30234	PIC16F872	DS30221	PIC18F2550	DS39637	PIC18F83J11		DS39770
PIC16C63		PIC16F873	DS30292	PIC18F4455		PIC18F84J11		
PIC16C64A		PIC16F874		PIC18F4550		PIC18F85J11		
PIC16C65A		PIC16F876	PIC18F2480	PIC18F63J90				
PIC16C66		PIC16F877	PIC18F4480	PIC18F64J90				
PIC16C67		PIC16F873A	PIC18F4580	PIC18F65J90				
PIC16C62B	DS35008	PIC16F874A	DS39582	PIC18F2510	DS39636	PIC18F83J90	DS39663	
PIC16C72A		PIC16F876A		PIC18F2610		PIC18F84J90		
PIC16C63A	DS30605	PIC16F877A	DS41291	PIC18F4510	DS39631	PIC18F85J90		
PIC16C65B		PIC16F882		PIC18F4610		PIC18F65J10		
PIC16C73B		PIC16F883		PIC18F2520	PIC18F65J15			
PIC16C74B		PIC16F884		PIC18F4520	PIC18F66J10			
PIC16C72	DS30390	PIC16F886	DS41250	PIC18F2585	DS39625	PIC18F66J15		
PIC16C73A		PIC16F887		PIC18F2680		PIC18F67J10		
PIC16C74A		PIC16F913		PIC18F4585	PIC18F85J10			
PIC16C76		PIC16F914		PIC18F4680	PIC18F85J15			
PIC16C77	DS41124	PIC16F916	DS39626	PIC18F2620	DS39626	PIC18F86J10		
PIC16C745		PIC16F917		PIC18F4620		PIC18F85J15		
PIC16C765		PIC16F946				PIC18F87J10		

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Device	Data Sheet	Device	Data Sheet	Device	Data Sheet	Device	Data Sheet
PIC16C773	DS30275	PIC17C42A	DS30412	PIC18F4685	DS39761	PIC18F65J50	DS39775
PIC16C774		PIC17C43		PIC18F6390	DS39629	PIC18F66J50	
PIC16C923	DS30444	PIC17C44	PIC18F6490	PIC18F66J55			
PIC16C924		PIC17C752	PIC18F8390	PIC18F67J50			
PIC16C925	DS39544	PIC17C756A	DS30289	PIC18F8490	PIC18F85J50	DS39778	
PIC16C926		PIC17C762		PIC18F6520	PIC18F85J55		
PIC16F72	DS39597	PIC17C766	DS39026	PIC18F6620	PIC18F87J50		
PIC16F73	DS30325	PIC18C242		PIC18F6720	DS39609	PIC18F66J11	
PIC16F74		PIC18C252		PIC18F8520		PIC18F66J16	
PIC16F76		PIC18C442		PIC18F8620		PIC18F67J11	
PIC16F77		PIC18C452	PIC18F8720	PIC18F86J11			
PIC16F87	DS30487	PIC18C601	DS39541	PIC18F6525	PIC18F86J16	DS39762	
PIC16F88		PIC18C801		PIC18F6621	PIC18F87J11		
PIC16F610	DS41288	PIC18C658	DS30475	PIC18F8525	PIC18F66J60		
PIC16HV610		PIC18C858		PIC18F8621	PIC18F66J65		
PIC16F616		PIC18F242	DS39564	PIC18F6527	PIC18F67J60		
PIC16HV616		PIC18F252		PIC18F6622	PIC18F86J60		
PIC16F627A	PIC18F442	PIC18F6627		PIC18F86J65			
PIC16F628A	DS40044	PIC18F452	DS41159	PIC18F6722	PIC18F87J60		
PIC16F648A		PIC18F248		PIC18F8527	PIC18F96J60		
PIC16F630	DS40039	PIC18F258		PIC18F8622	PIC18F6627	PIC18F96J65	
PICF676		PIC18F458	PIC18F8627	PIC18F97J60			
PIC16F631	DS41262	PIC18F1220	DS39605	PIC18F8722			
PIC16F677		PIC18F1320	DS39758				
PIC16F685		PIC18F1230					
PIC16F687		PIC18F1330	DS39599				
PIC16F689		PIC18F2220					
PIC16F690		PIC18F2330					
PIC16F684	DS41202	PIC18F4220					
PIC16F688	DS41203	PIC18F4320					

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1. Asynchronous Counter

When Timer1 is started or updated, the timer needs to see a falling edge from the external clock source before a rising edge can increment the counter. If writes to TMR1H and TMR1L are not completed while the external clock pulse is still high, Timer1 will miss counting the first clock pulse after the update.

One half of a 32.768 kHz external clock crystal period yields a 15.25 μs window to complete all writes to TMR1H and TMR1L (50% duty cycle). The number of instructions that can be executed within this window is dependent on FOSC, as shown in Table 1.

TABLE 1: FREQUENCY DEPENDENT INSTRUCTION EXECUTION AMOUNTS

Fosc	Tcy (μs)	Tcy within 15.25 μs
1 MHz	4	3
2 MHz	2	7
4 MHz	1	15
8 MHz	0.5	30
16 MHz	0.25	61
20 MHz	0.2	76
40 MHz (PIC18)	0.1	152

One of the following methods can be used to update Timer1 depending on whether all writes to TMR1H and TMR1L can or cannot be reliably completed before the clock pulse falling edge:

- If Timer1 *can* be reliably updated before the clock pulse falling edge occurs:
Update TMR1H and TMR1L as needed.
- If Timer1 updates can *not* be reliably completed before the clock pulse falling edge occurs:
 1. Wait for TMR1L to increment.
 2. When an increment is detected, immediately update TMR1H and TMR1L as needed.
Include the code between `RTCisr` and `Update`.

Code examples are given for the affected devices:

- PIC12/PIC14/PIC16 devices – Example 1
- PIC18 devices – Example 2

Both examples include code to wait for Timer1 to increment twice between the `RTCisr` and `Update` labels.

In PIC18 devices, it is not possible to reliably update Timer1 in a *low-priority* interrupt. A high-priority interrupt could occur at any time and unexpectedly delay the TMR1 update.

PIC18 devices also include Timer3 which is functionally identical to Timer1.

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EXAMPLE 1: PIC12/PIC14/PIC16 INTERRUPT SERVICE ROUTINE

```
IntVector   code 0x004      ; (3-4Tcy) fixed interrupt latency
movwf      W_temp          ; (1tcy) save W register contents
movf       STATUS,W        ; (1tcy) save STATUS register contents
movwf     Status_temp      ; (1tcy)
BANKSEL    PIR1            ; (2tcy) select correct SFR bank
btfss     PIR1,TMR1IF      ; (2tcy) did a Timer1 overflow occur?
goto      NextISR          ; (2tcy) no, check another interrupt source

; Insert the next 4 lines of code when TMR1 can not
; be reliably updated before clock pulse goes low
RTCisr:
    btfsc  TMR1L,0          ; wait for TMR1L<0> to become clear
    goto  $-1               ; may already be clear (loops for 0 to 30.5us)
    btfss  TMR1L,0          ; wait for TMR1L<0> to become set
    goto  $-1               ; (loops for 30.5us)

; If TMR1 update can be completed before clock pulse
; goes low, start update here
Update:
    bsf    TMR1H,7          ; reload for a 1 second overflow
    bcf    PIR1,TMR1IF      ; clear flag
    incf   Seconds,F        ; record second
    goto   Exit             ; return from interrupt

NextISR:   ; Another interrupt source...
    ....   ; code for other interrupts, if needed
    goto   Exit             ; return from interrupt

Exit:
    movf   status_temp,w    ; retrieve copy of status register
    movwf  status           ; restore pre-isr status register contents
    swapf  w_temp,f         ;
    swapf  w_temp,w         ; restore pre-isr w register contents
    retfie
```

EXAMPLE 2: PIC18 HIGH-PRIORITY INTERRUPT SERVICE ROUTINE

```
HIntVector code 0x0008      ; (3-4Tcy), fixed interrupt latency
goto      HighISR          ; (3Tcy) jump to high priority ISR code

code       ; unprotected code space
HighISR:
    btfss  PIR1,TMR1IF      ; (1Tcy) TMR1 overflow?
    goto  NextISR          ; (2Tcy) No, check another interrupt source

; Insert the next 4 lines of code when TMR1 can not
; be reliably updated before clock pulse goes low
RTCisr:
    btfsc  TMR1L,0          ; wait for TMR1L<0> to become clear
    bra    $-2               ; may already be clear (loops for 0 to 30.5us)
    btfss  TMR1L,0          ; wait for TMR1L<0> to become set
    bra    $-2               ; (loops for 30.5us)

; If TMR1 update can be completed before clock pulse
; goes low, start update here
Update:
    bsf    TMR1H,7          ; reload for next 1 second overflow
    bcf    PIR1,TMR1IF      ; clear flag
    incf   Seconds,F        ; record second
    retfie FAST

NextISR:   ; Another interrupt source...
    ....   ; code for other interrupts, if needed
    retfie FAST
```

REVISION HISTORY

Rev A Document (7/2007)
Initial release of this errata.

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NOTES:

Note the following details of the code protection feature on Microchip devices:

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